### MR-guided RT: Commissioning and Quality Control

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#### Disclosure

License agreement with Modus Medical Devices Inc. to develop a phantom for the quantification of MR image system-related distortions.

# Topics for MR-guided RT system commissioning & QC

□ MR data for RT planning and in-room guidance

- Spatial accuracy: system/scanner-related distortions
- Spatial accuracy: patient-induced (tissue susceptibility)
- Quantification of motion

### MR-guided RT systems: design specific

- RF noise
- Magnetic field coupling
- MR & radiation source: iso-to-iso registration
- □ System performance monitoring & Reporting
- Database record: in-house, commercial, cloud solutions

# MRI Guidance MR data for RT planning and in-room guidance MR images suffer of intrinsic distortions $\rightarrow$ affect geometric accuracy System | scanner - related: - B0 field inhomogeneities - Imaging gradients non-linearity Patient | object - induced: - Tissue magnetic susceptibility - Chemical shift Organ motion present → 4D composite distortion field The distortions can be treated as separate problems practically, no coupling b/w system and patient specific distortions

#### MRI Guidance

#### MR data for RT planning – System-related distortions

#### MR images suffer of intrinsic distortions $\rightarrow$ affect geometric accuracy

#### 1. B0 field inhomog ities

- High field homogeneity required for the static magnetic field Typical value: a few ppm in a 40-50 cm spherical volume

# Siemens Espree 1.5T - B0 field homogeneity specs

Homogeneity		
Volume	Guaranteed	Typical
10 cm DSV	≤0.05 ppm	0.01 ppm
20 cm DSV	≤0.2 ppm	0.08 ppm
30 cm DSV	≤1 ppm	0.8 ppm
$40 \times 40 \times 30 \text{ cm}^3$	≤2 ppm	1.2 ppm
$45 \times 45 \times 30 \text{ cm}^3$	≤4 ppm	2.8 ppm
	Standard deviation Vrms (Vo with highly accurate 24 plane	lume root-mean square) measured e plot method (20 points per plane).
$40 \times 40 \times 40 \text{ cm}^3$	≤5 ppm*	





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System-related distortions	MRI Guidance
Multiple MR scanner quantific	ation
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# MR data for RT planning – System-related distortions

MR images suffer of intrinsic distortions  $\rightarrow$  affect geometric accuracy

- Methods for quantifying the 3D distortion field
- a. Measurements using phantoms or linearity objects
- b. Theoretical evaluation using spherical harmonics
- c. Hybrid approach: measurements & harmonic analysis



Overlage and the distinguishing			
System-related distortions			
acquire identify control point locations	letermine distortion	correct M image	$\begin{array}{c} \text{AR} \\ \text{es} \end{array} \xrightarrow{\text{validate}} \\ \text{method} \end{array}$
		MR	СТ
	Winter Street		
- unsharp mask and Gaussian blur			
- adaptive thresholding			
- 3D Gaussian blurring in x and y			
- watershed: identify and analyze each d	ot		
- center of mass: control points coordina	ites		
	and the second		
JOURNAL OF APPLIED CLINICAL MEDICAL PHYSICS, VOLUME 11, NUMBER 1, WINTER 20	10		+++7
Investigation of a 3D system distortion correction m for MR images	ethod	1	++ 6
Teodor Stanesou, <sup>8</sup> Hans-Sonke Jans, Keith Wachowicz, Gino B. Fallon Medical Physics, Cross Career Institute, Edimonton, All, Canada teoderal discourt als ca			
Received 10 October 2008; accepted 14 September 2009			and and a second













# System-related distortions

#### Spherical harmonics analysis

A complete distortion correction for MR images: I. Gradient warp correction

Simon J Doran<sup>1</sup>, Liz Charles-Edwards<sup>2</sup>, Stefan A Reinsberg<sup>2</sup> and Martin O Leach<sup>2</sup>

Phys. Med. Biol. 50 (2005) 1343-1361



- Anm, Bnm are the spherical harmonic coefficients
- Provided by the manufacturer for a certain region of interest
- Example: 29 coeff for Gx and Gy | 7 coeff for Gz

# System-related distortions





- $u \in C(\overline{D}) \cap C^{2}(D)$  where  $\overline{D} = D \cup \partial D$  $g \in C(\partial D)$  is a continuous function
- Use of the harmonic properties of the 3D distortion vector field
- · Distortions are measured on the surface of the VOI
- Laplace's equation is solved to derive the full 3D field within the entire VOI

Med. Phys. 41 (11), N ber 2014 SU-F-J-154









# System-related distortions

MRI Guidance

#### Summary

- Manufacturers provide a 1<sup>st</sup> order correction (2D/3D)
  - Correction should be enabled in the protocols
- Detailed quantification of residual distortions needed
  - MR commissioning
  - Clinical implementation of clinical protocols
- Limited standardization and lack of user friendly solutions
  - Most of vendors offer phantoms with various features
  - In-house developments: reliability, efficient workflows
  - Routine monitoring, report & document







# Patient-induced distortions

### Methods for quantifying the distortion field:

- Measurement of B0 field distortion map

   double-echo GE sequence → phase diff of the 2 echoes
- 2. Correlating at least 2 images of the same sample without calculating or measuring the field
- 3. Numerical computations of the magnetic field on datasets converted into tissue susceptibility maps



# Patient-induced distortions

Tissue magnetic susceptibility (~ mm)

and the second	Max				0.5 T (5 mT/m	0	1	.0 T (5 mT/n	0	
to the staff	(ppm)	Max Mean distortion distortion (ppm) (ppm)	Range of distortion (ppm)	Max distortion (mm)	Mean distortion (mm)	Range of distortion (mm)	Max distortion (mm)	Mean distortion (mm)	Range of distortion (mm)	ppm offset
Body	5.48	0.43	9.36	0.55	0.04	0.94	3.29	0.26	5.62	-5.81
Bone	3.36	0.25	6.37	0.34	0.03	0.64	2.02	0.15	3.82	
ir cavities	5.66	0.92	9.96	0.57	0.09	1.00	3.40	0.55	5.98	
Body	2.99	0.41	5.37	0.30	0.04	0.54	1.79	0.25	3.22	-6.79
Bone	4.96	0.64	7.71	0.50	0.06	0.77	2.98	0.38	4.63	
Lung	5.56	0.71	8.85	0.56	0.07	0.89	3.34	0.43	5.31	
Body	3.98	0.54	6.42	0.40	0.05	0.64	2.39	0.32	3.85	-6.07
Bone	2.48	0.41	3.03	0.25	0.04	0.30	1.49	0.25	1.82	
Body	3.91	0.46	5.91	0.39	0.05	0.59	2.35	0.28	3.55	-6.12
Bone	2.54	0.47	4.02	0.25	0.05	0.40	1.52	0.28	2.41	
ir pockets	4.85	0.68	7.27	0.49	0.07	0.73	2.91	0.41	4.36	
in the second se	Body Bone cavities Body Bone Body Bone Body Bone pockets	Body         5.48           Bone         3.36           cavities         5.66           Body         2.99           Bone         4.96           Lang         5.56           Body         3.98           Bone         2.48           Body         3.91           Bone         2.54           pockets         4.85	Body         5.48         0.33           Bone         3.36         0.25           Gaty         2.99         0.41           Bone         4.96         0.64           Lang         5.56         0.71           Body         3.98         0.54           Bone         2.48         0.41           Bone         2.64         0.44           Bone         2.64         0.44           Bone         2.48         0.44           Bone         2.48         0.44           Bohy         3.91         0.46           Bone         2.54         0.47           pockets         4.85         0.68	Boby         5.48         0.43         9.36           Bose         3.6         0.25         6.37           cavities         5.66         0.22         9.96           Boby         2.90         9.41         5.37           Bose         4.66         0.41         5.37           Bose         4.66         0.61         7.81           Bose         2.66         0.71         8.85           Boby         3.06         0.54         6.42           Bose         2.68         0.41         3.03           Boby         3.01         0.46         5.91           Boby         0.51         0.68         7.27		Indey         5.48         0.41         9.36         0.55         0.04           Bases         3.56         0.92         6.37         0.54         0.09           carrines         5.66         0.92         6.97         0.57         0.09           Base         4.66         0.92         6.97         0.56         0.09           Base         4.66         0.21         5.71         0.56         0.06           Base         4.66         0.54         6.42         0.66         0.66           Base         4.66         0.54         6.42         0.66         0.66           Base         2.68         0.41         5.37         0.68         0.66           Base         2.48         0.44         5.01         0.39         0.03           Base         2.54         0.47         5.03         0.39         0.03           Base         2.54         0.47         6.08         7.27         0.68         0.09           Base         2.54         0.68         7.40         0.28         0.05	Indey         5.48         0.41         0.36         0.57         0.34         0.94         0.94           cavinis         5.66         0.25         6.37         0.34         0.35         0.54           cavinis         5.66         0.92         9.96         0.57         0.99         0.05           long         2.96         0.77         0.30         0.04         5.37           long         4.96         0.64         5.37         0.30         0.05         0.57           long         5.96         0.54         6.26         0.22         0.30         0.54         0.54           long         5.96         0.54         7.27         0.30         0.56         0.66         0.64           long         5.95         5.54         6.42         0.50         0.66         6.64           Rine         2.48         0.41         5.37         0.59         0.65         0.59           Biae         2.54         0.47         4.02         0.59         0.65         0.67           Biae         2.54         0.47         4.02         0.59         0.67         0.71	Indey         5.48         0.41         9.56         0.55         0.04         0.94         1.22           carrins         5.66         0.32         6.37         0.34         0.03         0.04         2.03           carrins         5.66         0.32         9.96         0.57         0.09         1.00         3.40           long         2.99         0.57         0.59         0.04         0.21         3.40           long         2.94         0.39         0.44         0.57         0.59         0.64         0.51           long         2.94         0.34         5.77         0.59         0.64         0.51         2.98           long         2.64         0.42         0.49         0.66         0.77         2.98           long         2.68         0.41         5.37         0.49         0.66         0.64         2.19           long         0.45         0.41         0.37         0.28         0.64         2.04         0.55         0.64         2.19           long         0.45         0.41         0.37         0.39         0.05         0.49         1.55           londer         2.54         0.47 <t< td=""><td>Indey         5.48         0.41         9.56         0.55         0.64         0.44         1.29         0.25           carinia         5.66         0.25         6.37         0.34         0.34         0.44         0.44         0.17         0.15           carinia         5.66         0.25         6.37         0.39         0.04         0.44         0.17         0.15           ling         2.96         0.57         0.39         0.04         0.44         0.57         0.25           ling         2.96         0.41         5.77         0.50         0.06         0.54         1.29         0.25           ling         2.96         0.51         6.42         0.66         0.64         2.94         0.33           ling         2.86         0.54         6.42         0.06         0.66         0.64         2.94         0.33           ling         2.48         0.41         0.30         0.26         0.66         0.64         2.94         0.33           ling         2.48         0.44         0.30         0.39         0.63         0.39         0.35         0.28         0.28           ling         2.44         0.45         &lt;</td><td></td></t<>	Indey         5.48         0.41         9.56         0.55         0.64         0.44         1.29         0.25           carinia         5.66         0.25         6.37         0.34         0.34         0.44         0.44         0.17         0.15           carinia         5.66         0.25         6.37         0.39         0.04         0.44         0.17         0.15           ling         2.96         0.57         0.39         0.04         0.44         0.57         0.25           ling         2.96         0.41         5.77         0.50         0.06         0.54         1.29         0.25           ling         2.96         0.51         6.42         0.66         0.64         2.94         0.33           ling         2.86         0.54         6.42         0.06         0.66         0.64         2.94         0.33           ling         2.48         0.41         0.30         0.26         0.66         0.64         2.94         0.33           ling         2.48         0.44         0.30         0.39         0.63         0.39         0.35         0.28         0.28           ling         2.44         0.45         <	

# Organ / target motion: lung

Case study: lung patient, 10 bins 4D CT

organ motion: - 2 independent steps

- 1. System distortions register anatomy to 3D field track dist as local target/organs move static field measured with phantom

# 2. Magnetic susceptibility - numerical methods

- anatomy specificdynamic distortion field

Total: combine contributions from 1 & 2









								MRI Gu	uidance	•
Orga	an / ta	arget moti	on: lung							
	_								1	1
B0 7-21	vie	Scanner-							1	1
D0 2-a	~13	related field	χ-induced	χ-11	iduced f	ield	Cor	nposite i	-ield	4
				0.35 T	0.5 T	1.5 T	0.35 T	0.5 T	1.5 T	1
		[mm]	[ppm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	T
Exhale	max	2.13	5.29	0.37	0.53	1.59	2.11	2.11	2.82	1
	mean	1.84	1.08	0.08	0.11	0.32	1.87	1.89	2.01	1
	range	0.46	6.50	0.46	0.65	1.95	0.45	0.46	1.23	
Inhale	max	2.09	5.64	0.39	0.56	1.69	2.20	2.29	2.99	1
	mean	1.89	1.36	0.10	0.14	0.41	1.92	1.94	2.10	L
	range	0.40	7.85	0.55	0.79	2.36	0.50	0.58	1.27	J
									100	-
		Scanner-							-	700
B0 v-a	vis	related field	γ-induced	χ-induced field			Composite Field			1
Doya	XI3		~	0.35 T	0.5 T	1.5 T	0.35 T	0.5 T	1.5 T	T
		[mm]	[ppm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	t
Exhale	max	2.13	4.24	0.30	0.42	1 27	2 15	2.18	2.62	1
	mean	1.84	1.19	0.08	0.12	0.36	1.86	1.87	1.97	L
	range	0.47	7.72	0.54	0.77	2.32	0.49	0.57	1.17	L
Inhale	max	2.09	3.73	0.26	0.37	1.12	2.08	2.11	2.57	1
	mean	1.89	1.13	0.08	0.11	0.34	1.90	1.91	2.00	L
	range	0.40	7.11	0.50	0.71	2.13	0.39	0.43	0.99	J
										-





### MR data for RT planning

#### MRI Guidance

- Vendor and application specific
- Large FOVs still posing practical issues for distortion field mapping
- Susceptibility-induced distortions minimized via protocol optimization
- Real-time correction limited
- Streamlining and clinical integration

#### MRI Guidance

MR data for Treatment Delivery - Patient setup verification & Tracking/Gating

Aim: Reliable quantification and validation of methods used for organ motion assessment (real-time or retrospective data availability)

- Real-time imaging:
  - 1D / 2D readily available, platform specific
  - $3D(?) \rightarrow 4D$  (3D+time): most techniques under development
- Retrospective 4D image data binning and image reconstruction
  - Available, implementation is vendor specific
  - Growing literature:  $2D \rightarrow 4D$ , 4D



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#### 4D MRI Retrospective - $3D \rightarrow 4D$

### MRI Guidance

3D fast acquisition with 4D image data sorting and reconstruction

- Similarity with 4D CBCT  $\rightarrow$  potential solution for motion quantification Strategies:
- Breathhold + multiple 3D acquisitions (< 15s) at diff respiratory phases
- Free breathing Continuous acquisition + post processing

# 4D MRI Retrospective - $3D \rightarrow 4D$

#### MRI Guidance

- 3D fast acquisition with 4D image data sorting and reconstruction
- Similarity with 4D CBCT → potential solution for motion quantification
   Strategies:
- Breathhold + multiple 3D acquisitions (< 15s) at diff respiratory phase</li>
- · Free breathing Continuous acquisition (radial sampling) + post processing

#### 4D MRI Dynamic

#### Strategies:

- Free breathing Multiple 3D scans with ~s time sampling, low image resolution
- Sparse/parallel imaging 3D acquisitions, good temporal sampling (?)











#### MRI Guidance

#### MR data for Treatment Delivery - Patient setup verification & Tracking/Ga itina

Aim: Reliable quantification and validation of methods used for organ motion assessment (real-time or retrospective data availability) rategies: 1D / 2D available, several proposed 4D techniques

#### ons and C

- Vendor implementation and application specific
- · 4D motion quantification of distortions still to be investigated
- · Motion phantoms & QA methods still to be developed
- Motion data integration in clinical workflows

Which is the main contributor to the MR image distortion field for RT applications?

20%	1.	MR main field (B0) inhomogeneity
20%	2.	Chemical shift
20%	3.	Tissue susceptibility
20%	4.	Imaging gradient non-linearities
20%	5.	Motion

# Topics for MR-guided RT system Commissioning & QC

- Open-source software for semi/auto-QC monitoring

- MR image distortion: system/scanner-related
- MR image distortion: susceptibility-induced

# MR-guided systems: design specific - RF noise

- Magnetic field coupling
- MR-radiation source system: iso-to-iso registration





#### MRI Guidance

### MR-linac systems

- MR needs to be isolated | Collects weak signal from patient
   Linac is a significant source of RF
- Solution
- Relocate linac main RF sources in adjacent rooms
   Enclose linac head or MR in a Faraday cage

- QC monitoring: MR scanner RF noise tests RF sniffer kit for troubleshooting







# MRI Guidance

### MR-linac systems

Linac is a large metallic structure, ferromagnetic components
 » MR imaging field homogeneity affected

#### Solutio

- Passive and/or active shielding
- Physical separation



## Princess Margaret MRgRT Project

QC monitoring:

- Simulation environment: baseline for B0 fringe field mapping

- Simulation environment: baseline for B0 fringe field mapping
   Establish margins of tolerance for sub-components
   MR scanner: active imaging field homogeneity
   Linac: beam optimal specs
   Couch: safety margins on pull forces, upgradability impact on MR



### Princess Margaret MRgRT Project

- B0 mapping for testing system performance
   Direct measurements to ensure B-field decoupling
   MR should stay within specs over time, all intended configurations
   Negligible impact from hysteresis/residual B-field related effects
   Measurements more often than for a standalone MR implementation



### MR testing & commissioning

#### MRgRT: MR Shimming Study

Methods:

- Siemens service procedures: Phantom Shim & Phantom Shim Check - B0 mapping technique: dual-echo GRE field mapping sequence
- Metrics: Brms, Bpp, FWHM water spectral peak
- Transient effects due to B-field priming of the environment
- The effects are reproducible
- MR shim stays within the specs outlined by Siemens/IMRIS



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# Princess Margaret MRgRT Project

- E Linac beam: Flatness & Symmetry v. Gantry angle rotation
   Direct measurements to ensure B-field decoupling
   Beam stirring servos turned on/off
   IC Profiler mounted on linac head via custom built accessory
   Look for remnant magnetization and transient effects





# Princess Margaret MRgRT Project

- Linac beam: Flatness & Symmetry v. Gantry angle rotation
   Direct measurements to ensure B-field decoupling
   Beam stirring servos turned on/off
   IC Profiler mounted on linac head via custom built accessory
   Look for remnant magnetization and transient effects



# Dosimetry in magnetic field

Electron trajectories perturbed by the presence of B0 → Lorentz force » effect = f(KE, B0, interface)







# Dosimetry in magnetic field

- electron trajectories perturbed by the presence of B0  $\rightarrow$  Lorentz force » effect = f(KE, B0, interface)



### MR-to-Radiation source isocenter registration

- Cylindrical phantom filled with water
- Scribe lines for alignment to lasers
- Circular film between two halves of phantom
- Wrap-around film strip
- Once MLC accuracy is established, imaging this phantom provides information about MR-RT isocenter alignment
- Once RT isocenter is established, MR isocenter coordinate shift is implemented in software

Courtesy of Olga Green



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### MR-to-Radiation source isocenter registration

- Designed for Elekta's Atlantic system
- MR-to-MV alignment
- Ceramic, non-conductive markers for MV
- 3D analysis to locate markers
- Automatic co-registration MR/MV
- Testing done at UMC, Utrecht
- MR image res: 1x1x1 mm3
- MV image res: 0.5x0.5x0.5 mm3
- Analysis mean error: ~0.3 mm





Images & info courtesy of M. Sell, M. Luzzaro (Elekta)

# MR-to-Radiation source isocenter registration

- Designed for IMRIS MR-linac system
  In collaboration with Modus Medical Devices
- · MR-to-kV and MV alignment
- Daily QA
- 3D analysis to locate markers
- Automatic co-registrationOngoing testing





# For MR-guided RT systems, which MR-related test is new and has to be added to the QC routine?

20% 1.	Magnetic field drift
20% 2.	Imaging-to-treatment isocenter co-registration
20% 3.	Center frequency
20% 4.	Image uniformity
20% 5.	Ghosting

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### Topics for MR-guided RT system Commissioning & QC

MR data for RT planning and in-room guidance

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- MR image distortion: susceptibility-induced
- Quantification of motion

MR-guided systems: design specific

- RF noise
- Magnetic field coupling
- MR-radiation source system: iso-to-iso registration
- System performance monitoring & Reporting
- Data base record: in-house, commercial, cloud solutions

### Topics for MR-guided RT system Commissioning & QC

#### Data record and Reporting

#### In-house:

- AAPM 2015 presentation: TU-G-CAMPUS-I-15
  - Developed by J. Yung et al at MD Anderson
  - Semi-automatic QC program
  - Analyze and record measurements
  - Built on open-source software (Linux, Apache, MySQL, Python)
  - Analysis performed on 27 MR scanner: 1.5/3T, GE/Siemens
  - <u>Tests:</u> geometric accuracy/linearity, position accuracy, image uniformity, signal, noise, ghosting, transmit gain, center frequency, magnetic field drift

# Topics for MR-guided RT system Commissioning & QC

#### Data record and Reporting

#### In-house / Commercial:

- AQUA
  - Developed at Princess Margaret (Toronto)
  - Initially aimed for linac QC
  - Can be configured to include MRI tests
  - Analysis is semi-automatic
  - Data record is manual
  - Allows for data trending, control charts
  - The software is currently developed by Acumyn (www.acumyn.com)

# Topics for MR-guided RT system Commissioning & QC

### Data record and Reporting

#### Commercial / Cloud:

- QUMULATE
  - Developed by Varian for linac QA
  - Store, visualize, manage QC dataArbitrary tests can be configured
  - Potential platform for MRI
  - Monthly/annual fee for service