

State-Of-The-Art of Current PET-AS Algorithms and Their Advantages and Limitations for Clinical Application

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Acknowledgements

Task Group Report


Classification and evaluation strategies of auto-segmentation approaches for PET: Report of AAPM task group No. 211

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Toward a standard for the evaluation of PET-Auto-Segmentation methods following the recommendations of AAPM task group No. 211: Requirements and implementation

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TG-211 PET-AS Summary

Method	Segmentation	Classification	Segmentation + Classification	Segmentation + Classification + Post-Processing
1.1.1.1	Yes	Yes	Yes	Yes
1.1.1.2	Yes	Yes	Yes	Yes
1.1.1.3	Yes	Yes	Yes	Yes
1.1.1.4	Yes	Yes	Yes	Yes
1.1.1.5	Yes	Yes	Yes	Yes
1.1.1.6	Yes	Yes	Yes	Yes
1.1.1.7	Yes	Yes	Yes	Yes
1.1.1.8	Yes	Yes	Yes	Yes
1.1.1.9	Yes	Yes	Yes	Yes
1.1.1.10	Yes	Yes	Yes	Yes
1.1.1.11	Yes	Yes	Yes	Yes
1.1.1.12	Yes	Yes	Yes	Yes
1.1.1.13	Yes	Yes	Yes	Yes
1.1.1.14	Yes	Yes	Yes	Yes
1.1.1.15	Yes	Yes	Yes	Yes
1.1.1.16	Yes	Yes	Yes	Yes
1.1.1.17	Yes	Yes	Yes	Yes
1.1.1.18	Yes	Yes	Yes	Yes
1.1.1.19	Yes	Yes	Yes	Yes
1.1.1.20	Yes	Yes	Yes	Yes
1.1.1.21	Yes	Yes	Yes	Yes
1.1.1.22	Yes	Yes	Yes	Yes
1.1.1.23	Yes	Yes	Yes	Yes
1.1.1.24	Yes	Yes	Yes	Yes
1.1.1.25	Yes	Yes	Yes	Yes
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1.1.1.99	Yes	Yes	Yes	Yes
1.1.1.100	Yes	Yes	Yes	Yes

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M University of Michigan Medical School **Classification of PET-AS**

- Use of pre- and post-processing steps
- Level of automation
- Segmentation/image processing algorithm employed and its assumptions and complexity

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M University of Michigan Medical School **Classes of PET-AS based on Algorithm**

- Fixed and adaptive threshold algorithms
- Advanced algorithms
 - Gradient-based segmentation
 - Region growing and adaptive region growing
 - Statistical-based approaches
 - Learning and texture-based segmentation
- Combined with image processing and/or Reconstruction
- Segmentation of multimodality images

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M University of Michigan Medical School **Thresholding algorithms I**

- Thresholding is expressed as follows (after images are converted to SUV):

$$\tilde{I} \in Y_T(I_i) = \begin{cases} 1, & I_i \geq T, \\ 0, & I_i < T, \end{cases} \quad I_i \in I_{\text{vox}}$$

where $Y_T(\cdot)$ the indicator function for threshold T

- T could be fixed or adapted

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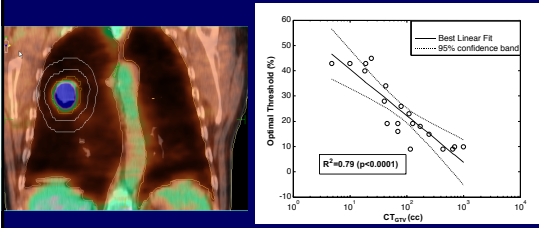
Thresholding algorithms II

Comments	Threshold Estimator
Dover, et al.'s single-parameter FTS (1977) is most notable for its use of the histogram's mode for more stable estimation of the background.	$T = a (I_{\text{max}} - I_{\text{bg}}) + I_{\text{bg}}$
Neethi, et al.'s single-parameter FTS (1983) uses the mean of voxels greater than 70% of the object's maximum. The use of the mean instead of the maximum updates reduces the variability.	$T = a I_{\text{max}, 70\% \text{max}} + I_{\text{bg}}$
Davies, et al.'s two-parameter FTS fit model (1977). The scaling parameter, I_{max} can be used as a mean-value or volume-based measure for an ATIS algorithm (2002).	$T = a + b \frac{I_{\text{max}}}{I_{\text{max}}}$
Schaefer, et al.'s two-parameter FTS (1993) This fit is extended from Haralick's scheme above (1977).	$T = a \frac{I_{\text{max}} \cdot \text{Volume} + b \cdot \text{Area}}$
Erdi, et al.'s two-parameter FTS (1983) It was noted that a fixed threshold of 42% worked well for large lung tumors, however, the authors go on to say that its use should be limited to homogeneous uptake distributions.	$T = a e^{-b(T)}$
Black, et al.'s two-parameter ATIS (1983). The use of the mean SDF to make the algorithm more robust to noise requires a threshold for its calculation.	$T = a + b I_{\text{max}} (V(T))$
Biel, et al.'s two-parameter ATIS (1986) The volume is the GTV defined by CT. This algorithm was shown to work for a range of tumor volumes in NSCLC.	$T = I_{\text{max}} (a + b \ln(CT_{\text{GTV}}))$
Jensen, et al.'s three-parameter ATIS (1983). The parameters were fitted from phantom data. The volume parameter requires a threshold.	$T = \sqrt[3]{V} + b \frac{I_{\text{max}}}{I_{\text{max}}} + c$
Rathbun, et al.'s four-parameter ATIS (1983). The fit used Monte Carlo simulation results to avoid cold-well effects.	$T = I_{\text{max}} (a + b V(T) \mu^d)^{1/d}$
Burger, et al.'s Background Subtracted Lesion (BSL) (2003). His means as segmentation but rather a volume estimation scheme, an equivalent volume threshold can be found (Liu et al. 2003) Note that this method tends to overestimate the volume by including spill-out.	Procedure: T , such that the volume from this threshold matches the BSL volume derived from histogram analysis.

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Adaptive thresholding example



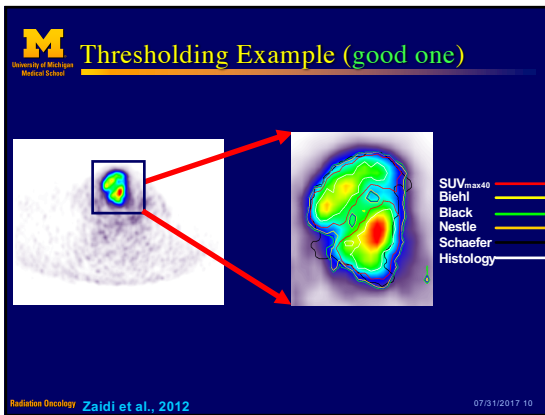
Radiation Oncology Bichl et al., JNM, 2006 07/31/2017 8

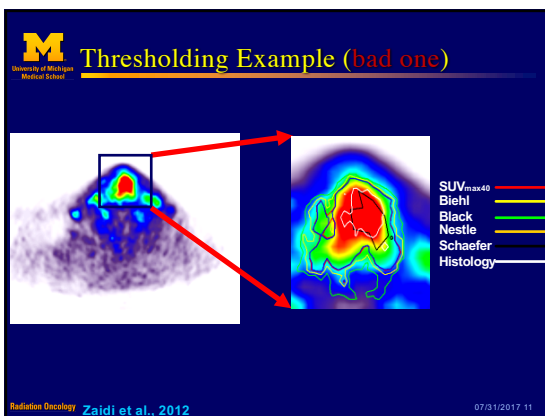
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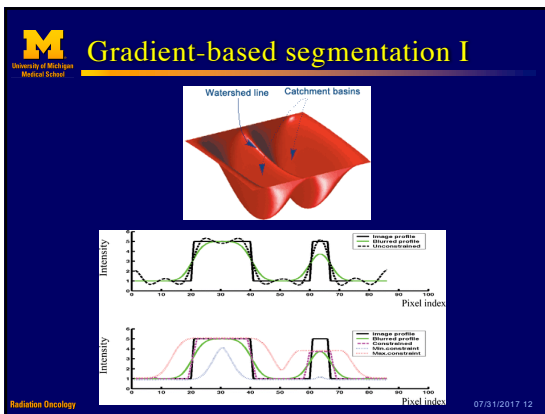
Thresholding algorithms III

<p>Pros</p> <ul style="list-style-type: none"> • Simple • Easy to implement 	<p>Cons</p> <ul style="list-style-type: none"> • Assumes well defined object boundary and uniform background • Sensitive to imaging acquisition parameters (resolution, contrast, noise)
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Pros

- Efficient
- Easy to implement

Cons

- Sensitive to imaging acquisition parameters (resolution, contrast, noise)
- Requires pre-processing (denoising/deblurring)

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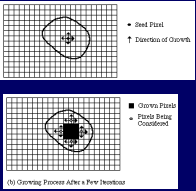
M University of Michigan Medical School **Gradient-based segmentation III**

	Axial	Coronal	Sagittal
Gradient-based method			
Threshold-based method			

Radiation Oncology Geets et al., 2007 07/31/2017 14

M University of Michigan Medical School **Region growing and adaptive region growing I**

- Generally,
 - 1) Start by a voxel (**seed**)
 - 2) Check neighboring voxels and add them if they are **similar** to seed
 - 3) Repeat (2) until no voxel can be added



• Seed Point
↑ Neighbors of Current

■ Current Point
• Neighbors of Current

(A) Gonzalez, Thoreau, Arni & Park (2006)

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M University of Michigan Medical School **Region growing and adaptive region growing II**

Pros

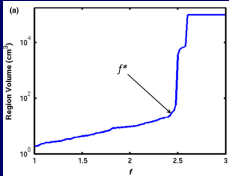
- Efficient
- Easy to implement

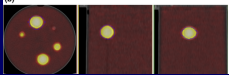
Cons

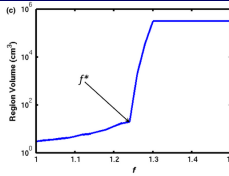
- Sensitive to seed selection (initialization)
- Adaptation criteria can vary by application

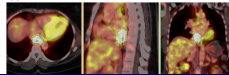
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M University of Michigan Medical School **Region growing and adaptive region growing III**

(a) 

(b) 

(c) 

(d) 

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M University of Michigan Medical School **Statistical**

• Bayes rule

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

• Fuzzy Locally Adaptive Bayesian (FLAB)

$$d^c(x|y_c) = \frac{p_{c,c}^{d,c} f^{c-1}(y_c|x)}{p_{c,0}^{d,c} f^{c-1}(y_c|0) + p_{c,1}^{d,c} f^{c-1}(y_c|1) + \left(1 - p_{c,0}^{d,c} - p_{c,1}^{d,c}\right) \int_0^1 f^{c-1}(y_c|\theta) d\theta}$$

Where d is posterior distribution with respect to class c a given voxel
 f ; f is probability density distribution (Pearson system) and p is prior probability

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Pros

- Robust
- Flexible
- Incorporate prior knowledge (Bayesian)
- Can perform well with heterogeneous uptake distributions

Cons

- More complex
- May require statistical knowledge
- Iterative (slow convergence)

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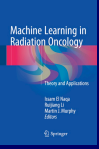
M University of Michigan Medical School **Statistical III**

Ground truth	PET	FLAB	FCM	Thresholding

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M University of Michigan Medical School **Learning and texture-based segmentation algorithms I**

- Applies machine learning techniques
 - Supervised (NN, SVM, decision trees, Random forests, etc)
 - Unsupervised (PCA, clustering (FCM, K-means, etc))
- Could be feature-based or voxel-based



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M Learning and texture-based segmentation algorithms I
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Pros

- Robust
- Accurate
- Can perform well with heterogeneous uptake distributions

Cons

- May require training (supervised)
 - Needs ground truth (teacher)
 - Time consuming
- Risk of overfitting
- May depend on extracted features or selected parameters

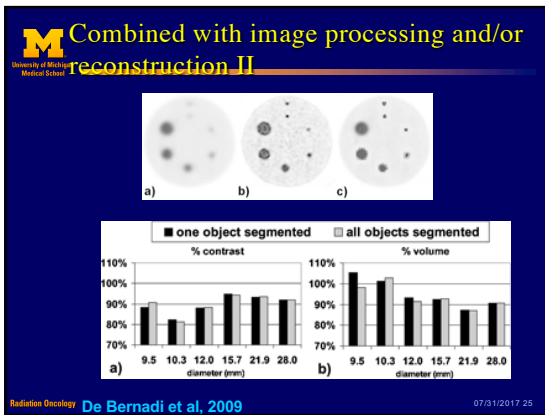
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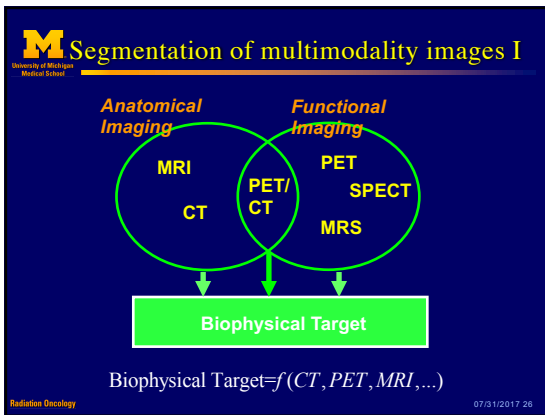
M Learning and texture-based segmentation algorithms II
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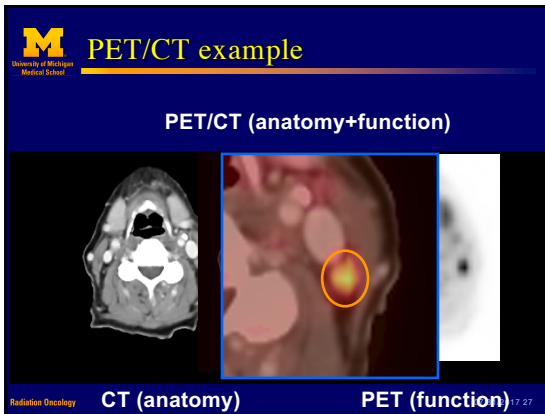
Radiation Oncology Berthon et al, 2016 07/31/2017 23

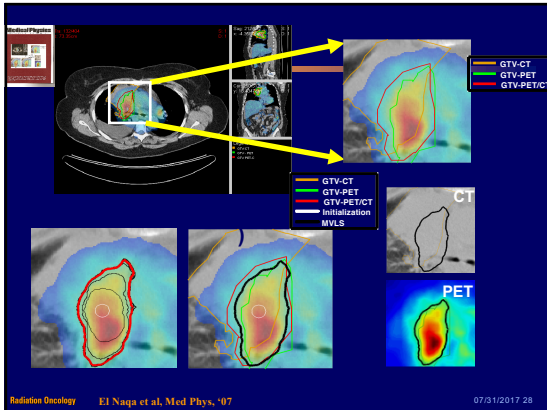
M Combined with image processing and/or reconstruction I
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Radiation Oncology De Bernadi et al, 2009 07/31/2017 24









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Summary of automated lesion detection in PET

Category	Characteristics	Limitations
<i>Thresholding techniques</i>	Most frequently used due to their simple implementation and high efficiency.	Hard decision-making. Too sensitive to PVE, tumour heterogeneity, and motion artifacts. Some methods focus on volume, others focus on intensity differences. Combination of both seems to provide best results [81].
<i>Variational approaches</i>	Suboptimal accuracy, boundary continuity, and relatively inefficient. They are mathematically well developed and allow for incorporation of priors such as shape.	Sensitive to image noise. As a PDE, stability and convergence could be subject to numerical fluctuations, especially if the parameters are not properly selected.
<i>Learning methods</i>	Utilize pattern recognition power. Two main types: supervised (classification) and unsupervised (clustering).	Computational complexity especially in supervised methods, which require time consuming training. Feature selection beside commonly used intensity is a flexibility but can also be a challenge.
<i>Stochastic models</i>	Exploit statistical differences between tumour uptake and surrounding tissues. Most natural to deal with the noisy nature of PET.	Effect of initialization and convergence to local optimal solutions are concerns, especially when compromise are made to improve efficiency.

Zaidi & El Naqa, Eur J. Nuc Med, 2010.
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Conclusions
- Different **PET-AS** algorithms have their own **pros/cons** and selection of 'best' one is a **compromise** and a matter of convenience
 - Most PET-AS algorithms are **not commercially** available software
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