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Fast and Furious: Path to Effective MRgART

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Disclosure

I receive research grants from Varian Medical Systems and VisionRT

I am a founder of Celestial Medical

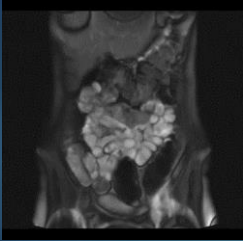
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MRgART: From image to treatment

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graph TD; A[Image acquisition/reconstruction] --> B[Segmentation]; B --> C[Treatment planning/optimization]; C --> D[QA]; D --> E[Delivery];
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Anatomy is faster than your "car"



The straight story, 1999 David Lynch

MR guided adaptive RT can be slow

Process step	Median (min-max) time (minutes)
Room patient and acquire image used for re-plan	9 (5-30)
MD approval of initial setup	7 (3-18)
Adaptive re-contouring	10 (5-22)
Adjust plan and perform quality assurance (QA)	14 (8-40)
Total	54 (34-99) *

Time spent in adaptive MR guided radiotherapy
 *Including ~14 minutes beam delivery time using Co-60
 Lamb et al. Cureus. 2017 Aug 27;9(8)

Improving MRI acquisition time

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Spin Echo Turbo Spin Echo (TSE)

1. Squeeze in more k-space read out from one excitation

Echoplanar imaging Single-shot Turbo spin Echo imaging (HASTE)

Gradient Echo Fast Gradient Echo (F-kgSE) Steady state free Balanced steady state free precision (True-FISP)

2. Push for shorter repetition time (TR)

Parallel imaging Image domain PI (SENSE) K-space PI (GRAPPA)

3. Exploit the multicoil hardware

MRI acquisition: too much information too little time

of phase encoding steps in y
(A: number of averages)

uFisp 3D sequence without
minutes

parallel acquisition, improve the reconstruction

Parallel imaging

Big k-space, Small k_y spacing

Small k-space, Small k_y spacing

Big k-space, Big k_y spacing

Full FOV Full Resolution (a)

Full FOV Lower Resolution (b)

Smaller FOV Full Resolution (c)

$$F_1 = A_1 + B_1 = I_1 \times C_{1a} + I_2 \times C_{1b} + C_{1c}$$

$$F_2 = A_2 + B_2 = I_2 \times C_{2a} + I_1 \times C_{2b} + C_{2c}$$

$$F_3 = A_3 + B_3 = I_1 \times C_{3a} + I_2 \times C_{3b} + C_{3c}$$

$$F_4 = A_4 + B_4 = I_2 \times C_{4a} + I_1 \times C_{4b} + C_{4c}$$

SENSE

Multiple coil elements each acquires part of the k-space resulting in aliased images that are unraveled using SENSE

Frequency domain for GRAPPA, typical acceleration 2-4

Deshmane et al. J Magn Reson Imaging 2012;36:55-72.



MRI acquisition time

- Scan time = TR·Ny·N·NSA
- (TR: repetition time; Ny: number of phase encoding steps in y direction; N: number of slices; NSA: number of averages)
- Typical full field-of-view ViewRay TruFisp 3D sequence without acceleration
Scan time = 3.37ms·334·334=6.26 minutes
- Without compressed sensing, with lower resolution, smaller FOV, parallel imaging and Partial Fourier
Scan time = 2.9ms·180·160/(2·0.75·0.75)=43 seconds, barely fast enough for breath hold MRI

Classic sampling theorem: Nyquist's Rate

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► Perfect recovery requires $f_s \geq 2f_b$, lower sampling rates result in aliasing artifacts.



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The leap

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	Traditional sensing	Compressive Sensing
Sampling Frequency	$\geq 2f_b$	$< 2f_b$
Recovery	Low pass filter	Convex or non-convex optimization

Donoho, IEEE Transaction on Information Theory 2006

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The optimization problem

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$$\min_u \| \Psi u \|_1, \text{ s.t. } \| F_\mu u - d \|_2^2 \leq \sigma$$

Enforce sparsity Fidelity or data consistency term

- Since the optimization problem is under-determined due to the undersampling, a regularization term is used.
- A popular option for the regularization term is total variation that enforces sparsity by encouraging tissue piecewise smoothness
- Compressed sensing is intricately related to parallel imaging and k space sampling trajectories

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More Efficient k-Space Sampling

2D sequences

3D sequences

Ferreira et al. J Cardiovasc Magn Reson. 2013
Frank Riemer Magnetic Resonance Materials in Physics 2014

- Using fewer phase encoding lines to cover the k-space while minimizing the undersampling artifacts
- More heavily sample the center of the k-space where the contrast information resides.

MRI acquisition time

- Scan time = TR·Ny·N·NSA
- (TR: repetition time; Ny: number of phase encoding steps in y direction; N: number of slices; NSA: number of averages)
- Typical full field-of-view ViewRay TrueFisp 3D sequence without acceleration
Scan time = 3.37ms·334·334·6.26 minutes
- Without compressed sensing, with lower resolution and FOV
Scan time = 2.9ms·180·160/(20.75·0.75)=23 seconds, barely fast enough for breath hold MRI
- With aggressive compressed sensing: 23/8=2.875 seconds
Speed sufficient for online adaptive RT. Image quality may show noticeable degradation
- 10X acceleration is still needed for real time 3D image
- To make this happen, capture the motion

Joint motion estimation using Primal Dual Algorithm with Linesearch (J-PDAL)

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$$\min_{\substack{u_1, \dots, u_N \\ v_1, \dots, v_N \\ w_1, \dots, w_N}} \sum_{t=1}^N \frac{1}{2} \|S_t F(I_0 + \partial_x I_0 \otimes u_t + \partial_y I_0 \otimes v_t + \partial_z I_0 \otimes w_t) - b_t\|_2^2$$

Fidelity term

$$+ \lambda \sum_{t=1}^N \|Du_t\|_1^{(\alpha)} + \|Dv_t\|_1^{(\alpha)} + \|Dw_t\|_1^{(\alpha)}$$

Enforce sparsity on DVF

$$+ \delta \sum_{t=1}^{N-1} \frac{1}{2} \|u_{t+1} - u_t\|_2^2 + \frac{1}{2} \|v_{t+1} - v_t\|_2^2 + \frac{1}{2} \|w_{t+1} - w_t\|_2^2$$

Enforce temporal continuity on DVF

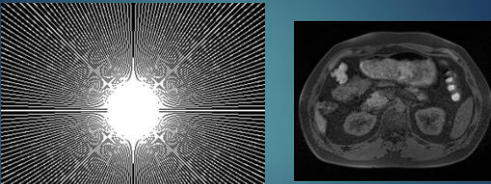
subject to $-\epsilon \leq u_t, v_t, w_t \leq \epsilon, \text{ for } t = 1, \dots, N.$

Zhao et al. AAPM 2018 TU-GH-KDBRC-7

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Radial sampling pattern

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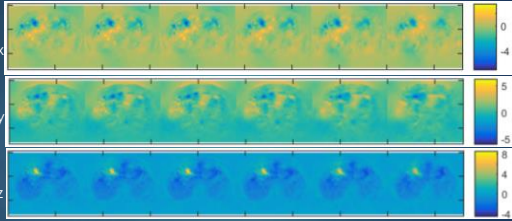


3D VIBE breath hold images of EOE and EOJ

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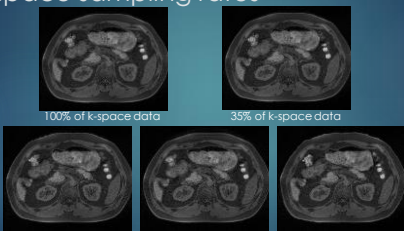
DVF Reconstructed with down-sampled k-space

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Sampling rate % 100 35 18 10 5 2

Images reconstructed with various k-space sampling rates



100% of k-space data 35% of k-space data 10% of k-space data 5% of k-space data 2% of k-space data

Motion model based reconstruction

Huttinga et al. ISMRM 2018

Motion model based reconstruction

Step 1. Low-resolution snapshot data from a moving object. Using a fast single-shot readout (e.g. TR=20ms), this implies a high-resolution 3D acquisition at a rate of 1/TR=50 Hz.

Step 2. Reconstruct the desired motion-fields from the snapshots and a low-resolution reference image. Noise and small motion-artifacts will be reduced in these images, making the proposed method more robust.

Step 3. Reconstruct high-resolution 3D images by applying the reconstructed motion-fields to a high-resolution reference.

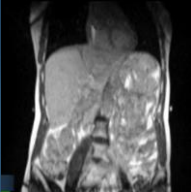
Huttinga et al. ISMRM 2018

8 volume/s, potentially accelerated to 50 volume/s


Huttinga et al. ISMRM 2018

Segmentation: a bigger time sink

Treat image



Unacceptably inaccurate heart contour from deformable registration



- Deformable registration can carry the segmentation but the results can be inaccurate, particularly with aggressively accelerated images
- Manual contour editing is time consuming and major contributor of the slow adaptive procedures

Automated MR pancreas segmentation

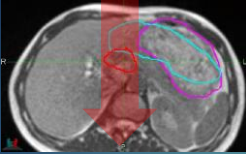
HASTE					
VIBE (pre-contrast)					
VIBE (post-contrast)					
Method	MSM	DRLS	QC	DL	Manual

- >82% DI is achieved using a machine learning method¹
- Comparable to manual segmentation reproducibility²
- Recent deep learning segmentation suggests that once the neural networks are trained, multiple organs can be segmented in <10 seconds.³

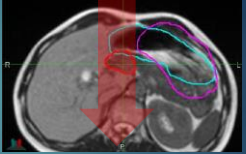
1. Gou et al. Adv Radiat Oncol. 2016; JM Sep; 1(3): 182-193.
 2. Noel et al. Med Dosim. 2014; 39(3): 212-217.
 3. Tong et al. AAPM 2018 110-CF33-GeO-15-4

MRgART: are beams always reusable?

Planning MRI




Treatment MRI



- The AP beam used in the planning MRI would over irradiate the more medially distended stomach at the treatment. Patient subsequently developed stomach ulcer.
- Beam orientation or full arc optimization are needed to take advantage of the new knowledge of internal anatomy.

Feasible fantasy




Process	Time (minutes)
Room p	5 min
MD app	7 min
Adaptiv	1 min
Adjust p	1 min, longer with 800 or VMAT
Total	24 min

Activatable in the near future

Ultimate form of MR guided adaptive RT

Phase 1



- Real time 3D images
- Real time segmentation of the tumor and the OARs
- Real time beam orientation or VMAT optimization

<http://shenglab.dgsom.ucla.edu/>

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2017



2018

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