



















Development of deblurring methods

Self-masking subtraction tomosynthesis Chakraborty et al, 1984

> Selective plane removal Ghosh Roy et al, 1985

Matrix inversion tomosynthesis Dobbins, 1986

TACT and image restoration Webber, Ruttimann, 1990s

Filtered backprojection 2000s

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ML-EM Reconstruction: Likelihood Function

Likelihood Function

•L=P(Y|): probability of getting the measured projections Y, given a 3D model

• $\mu^{(n)}$ is updated iteratively so that $L^{(n+1)} > L^{(n)}$

•The reconstruction solution is the 3D attenuation distribution model that maximizes L

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Advantages/disadvantages of iterative methods relative to FBP/MITS

- Better modeling of system, including truncation effects
- · Potentially better noise properties
- Potentially better with fewer projections
- Much slower computationally than FBP or MITS

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