Technologies Addressing the Range Uncertainty of Ion Therapy: Positron-Emission-Tomography

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PET-based verification

- Basic principle
- Clinical implementation and experience
- R&D challenges (and opportunities)
- Conclusion and outlook



- Primary ions are stopped *somewhere* within the patient, with dose and range mainly dependent on Coulomb interaction
- Nuclear reactions induce measurable emerging radiation



• Secondary radiation can be used as surrogate signal to infer information on the beam range and treatment delivery

Only Positron-Emission-Tomography clinically investigated so far

In-vivo PET-based verification

Int



(projectile fragmentation only for Z>1)

 β^+ -emitter yield (¹⁵O, ¹¹C,..., with T_{1/2} ~ 2, 20,... min) as by-product of irradiation

$A(r) \neq D(r)$

Tradeoff between **better spatial correlation** (¹²C) and **stronger signal** (*p*)

Dose-guidance from comparison of **measured** vs **expected** β⁺-activity



K. Parodi et al, IEEE TNS 2005





In-beam PET

- Patient in treatment position
- + Detection of short lived emitters (¹⁵O)
- No prolongation of treatment session
- Morphological information from planning CT
- Limited-angle detection
- High integration costs
- Suitable for pulsed beam delivery (measurement only in beam-off times)

Installation at GSI Darmstadt used clinically for scanned ¹²C ions

Enghardt, ... Parodi ... Nucl Instrum Meth A 2004; Parodi et al Nucl Instrum Meth A 2005

Clinical implementation (I): ibPET

 $\frac{dE}{dE} = \kappa \rho \frac{Z}{dE}$

Experience from ibPET at GSI

- + Validation of TPS CT-range calibration
- Detection of mispositioning and anatomy changes with indirect dose quantification
- + > 90% sensitivity / specificity in detecting
 ±6 mm range changes (in-silico trial)
- Minor degradation from washout
- Non-quantitative imaging, severe limitedangle artifacts in extra-cranial sites
- Low counting statistics

Detection of over-range due to anatomy chage



Initial CT-range cal. Improved CT-range cal.



PET-based dose quantification



Enghardt, ... Parodi ... Nucl Instrum Meth A 2004; Parodi PhD Thesis 2004; Fiedler et al, PMB 2010

MU LUDWIG-MAXIMILIANS-UNIVERSITAT Clinical implementation (II): offline

 $\frac{dE}{dE} = \kappa \rho \frac{Z}{dE}$

Offline PET-CT

- + Full ring scanner
- + Comparably low cost
- CT-image for co-registration (extra dose)
- Patient re-positioning (if not using shuttle)
- ~ 5–20 min time delay from irradiation to imaging (washout, counting statistics)
- Long scan time (~ 20-30 min)







Parodi et al, IJROBP 2007; Parodi et al, IEEE CR 2011; Bauer,..., Parodi, Radiother Oncol 2013



Tumor location

Cervical spine

Head Thorax Eye Abdomen Prostate

Clinical implementation (II): offline PET/CT

Experience from offline PET/CT at MGH (p)

- + Activation detected in all subjects
- + Washout modeling included in PET prediction
- Feasibility of ± 3mm range monitoring in well co-registered and low perfused tissues (H&N)
- Low counting statistics
- Improper tissue classification from CT alone

Motion

- Limitations of universal washout modeling
- Co-registration and motion blurring in extra-cranial sites

Biologic

washout



Scattered protons

Parodi et al, IJROBP 68, 2007; Knopf, Parodi et al, PMB 54, 2009; Knopf, Parodi et al, IJROBP 72, 2011

MC

uncertainties



Clinical implementation (II): offline PET/CT

At HIT (p, ¹²C) similar findings as MGH, moreover

- + Feasibility and reproducibility of shuttle transport
- Enhanced signal in distal part of the field due to ¹¹C projectile fragments from ¹²C ion beam
- Feasibility of range monitoring also in extracranial sites, detection of mispositioning
- + Enhanced signal in necrotic areas ("markers")
- Even lower counting statistics for ¹²C ions than p
- Challenges of 4D gated imaging at low counts



Scanned ¹²C ions Calc. PET on TP-CT 20 40 60 60 100 120 140 Meas. PET/CT Calc. PET on PET-CT

Bauer et al, Radiother Oncol 2013, Kurz et al, Radiother Oncol 2012



Clinical implementation (III): in-room

= [ln($\frac{2m_ev^2\gamma^2}{2m_ev^2\gamma^2}$

In-room PET

- + Patient in treatment position
- + Full ring scanner possible
- + Few minutes acquisition sufficient
- Patient throughput
- Co-registration uncertainties if moving table





Nishio et al IJROBP 2010, Zhou et al PMB 2011, Shakirin et al PMB 2011, Min et al IJROBP 2013



Clinical implementation (III): in-room PET

Experience from dual-head in-room PET at NCC Kashiwa (p)

- + 200 s acquisition after end of irradiation found sufficient for imaging
- + Detection of inter-fractional delivery / anatomy changes
- Assessment of reproducibility (daily activity compared to reference meas.)
- Small planar system optimised for animal imaging, limited FOV
- No acquisition possible during beam-on time



Scattered protons





Nishio et al, IJROBP 2010; Courtesy of T. Nishio, NCC Kashiwa



Clinical implementation (III): in-room PET

Experience from full-ring in-room PET at MGH (p)

- + 5 min measurement started 2 min after irradiation end similar to 20 min scan
- + Range agreement mostly within ±3 mm (4 11 mm rms)
 - ~ 2 mm co-registration errors despite robotic couch and radioactive markers
- Limited bore of scanner (only head and pediatric cases)









Zhou et al PMB 2011, Min et al IJROBP 2013



Remaining limitations of PET-based verification

- Inaccurate prediction of activity distributions due to insufficient knowledge of nuclear reaction cross sections and tissue composition
- Degradation of activity distributions by washout and organ motion

R&D challenges

- Time-consuming evaluation requiring well trained staff
- Imaging performances and integration costs for on-site implementations



Modeling of PET prediction

Ongoing efforts to

- Improve MC prediction via experimental based adjustement of β+ activation cross sections (only feasible for *p*)
- Speed up calculation with analytical approaches, ideally using same pencil beam algorithms as TPS
- Overcome limitations of CT-based tissue classification by using MRI information or Dual Energy CT







Washout and motion blurring

Ongoing efforts to

- Improve washout modeling on the basis of animal studies
- Assess experimentally the potential and limitations of time-resolved 4D PET for monitoring motion-compensated delivery at different facilities and PET installations



PET/CT after p/¹²C @ HIT Data analysis in progress



Stützer et al, PMB 2013



Automated range assessment

Ongoing efforts to establish

 Robust, automated range assessment from PET distributions based on profile shift analysis or % fall-off in BEV (meas. vs calc., meas. vs meas.) In-beam PET @ GSI





Helmbrecht et al, PMB 2012

Similar approach for in-room PET @ MGH (Min et al, IJROBP 2013)

Decision support system for clinical workflow

Offline PET/CT @ HIT







Range shift in mm

Unholtz, ..., Parodi, IEEE MIC Conf. Rec. 2011



Hardware improvements

Full ring solutions

- Prototype small bore PET/CT scanner being commissioned at MGH prior to clinical usage
- Small scale in-beam full ring scanner prototypes being developed and tested with stable and radioactive beams at NIRS







Images courtesy of H. Paganetti, MGH Boston, and Taiga Yamaya, NIRS Japan



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Dual head solutions

UDWIG

MAXIMILIANS

- New detector developments towards ultra-fast Time-of-Flight (TOF) in-beam PET
- Small scale in-beam prototypes being developed and tested



Experimental set-up of TU-Delft group @ HIT



Philips dSiPM and LYSO crystals



Images courtesy of D. Schaart and P. Cambraia Lopes, TU Delft



- Clinical investigations of PET monitoring being reported for different centers with different ions and delivery systems, as well as different scanners (mostly adapted from nuclear medicine or small animal imaging)
- Despite promising results (± 3mm range verification accuracy in favorable H&N locations), several issues remain (counting statistics, washout, co-registration and motion in extra-cranial sites, ...)
- Several groups are pursuing methodological improvements, but major advancement being expected by next generation in-beam PET scanners specifically optimized for this application
- Although many promising new techniques are on the horizon, PET could still play a role due to its intrinsic 3D, molecular imaging capabilities when properly used to detect the major ¹⁵O contribution in the tumour

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GEFÖRDERT VOM

Bundesministerium ür Bilduna und Forschung

you for your attention hank



Automated range assessment

Profile shift analysis ^(*) or % fall-off in BEV





PET – Dose difference



Min MGH

Unholtz, Bauer, ..., Parodi, IEEE MIC CR 2011, Helmbrecht et al, PMB 2012

Indirect PET-guided dose quantification

Indirect estimation of ¹²C dose deviation from in-beam PET



Parodi Ph.D. Thesis, 2004; Enghardt, Parodi et al, Radiother Oncol, 2004

Offline PET/CT clinical experience at MGH

		# of patients	Dose / field [GyE]
	head	12	0.9-3
	eye	1	10
	C-spine	3	0.6-2.5
	T-spine	1	1.8
	L-spine	2	0.9-2
	sacrum	2	1-2
	prostate	2	2
	TOTAL	23	0.6-10

	Challenge						
Tumor location	Biologic washout	Motion	MC uncertainties	Beam direction	CT fusion	Organ position	Cumulative weighting factor
Cervical spine Head	1	ł	1	1	2	ł	7
Thorax Eye	2 2	3	2 2	1 1	2	2	12 12
Abdomen Prostate	3	3	3	2 2	3	2	16 17

Parodi et al, IJROBP 68, 2007; Knopf, Parodi et al, PMB 54, 2009; Knopf, Parodi et al, IJROBP 72, 2011

In-beam PET for ¹²C ion therapy at GSI



> 400 patients

For every fraction (typically 20 d @ 1Gy)



Verification of

- Beam range
- Lateral position

In case of deviation

Timely reaction



Once



Enghardt, ... Parodi ... Nucl Instrum Meth A 2004; Parodi et al Nucl Instrum Meth A 2005

Accuracy of in-beam PET range verification?

"In-silico" trial on patient treated at GSI (Head&Neck)

Range modification (up to \pm 6mm) and visual evaluation by experienced person



	Overrange detection	Underrange detection
Specificity	96 ± 2 %	96 ± 2 %
Sensitivity	91 ± 3 %	92 ± 3 %



Fiedler et al PMB 2010