

Overview of CyberKnife Radiosurgery

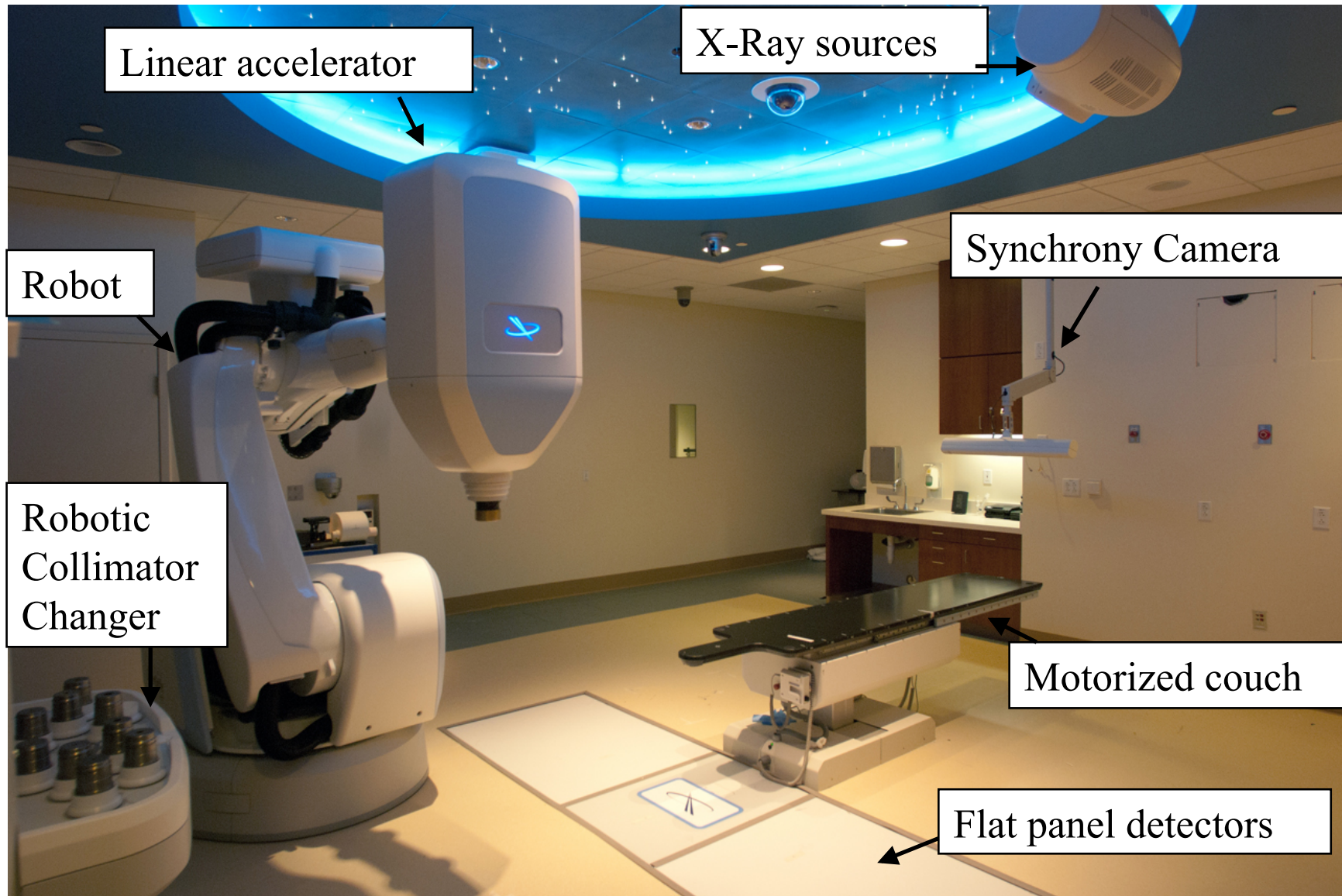
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Learning Objectives

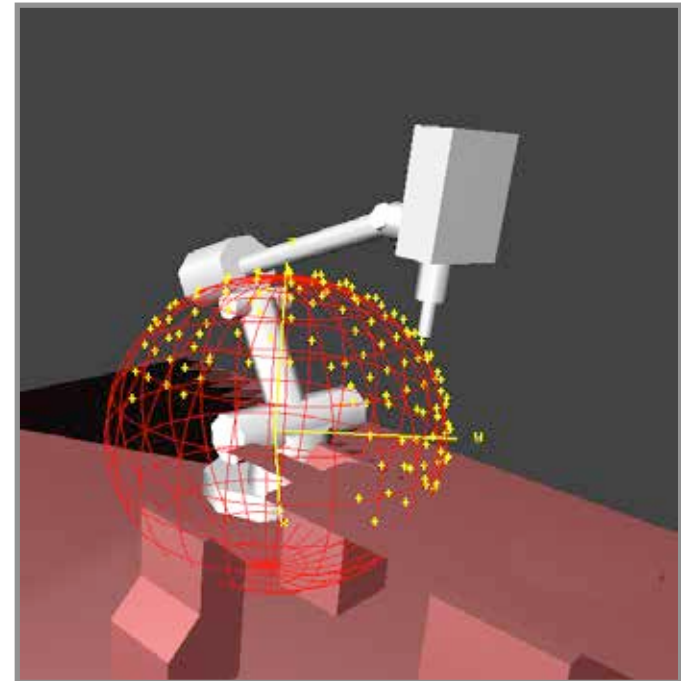
- ❑ Review operating principles of CyberKnife
 - ❑ System components
 - ❑ Target tracking
 - ❑ Treatment delivery
- ❑ Demonstrate how to create a treatment plan for an intracranial target
- ❑ Discuss QA tests

The CyberKnife System



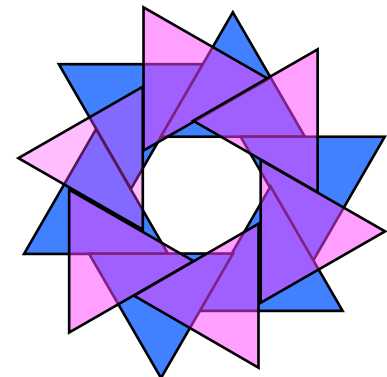
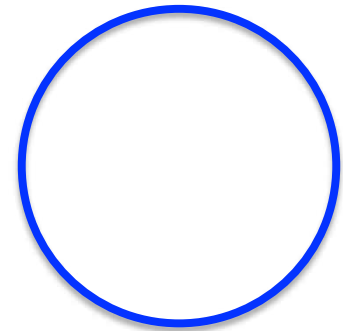
Linac and Robot

- ❑ Linac:
 - ❑ 6 MV x-rays
 - ❑ Dose rate up to 1000 MU/min
 - ❑ No-flattening filter
- ❑ Robot:
 - ❑ 6 axis joint motion
 - ❑ Non-isocentric beam delivery
 - ❑ Predefined path sets
 - ❑ Nominal SAD 80 cm



Collimator system

- ❑ Fixed:
 - ❑ 12 tungsten cone, 5-60 mm diameter
 - ❑ Multiple path traversal
 - ❑ Advantages: Sharper penumbra, no field size uncertainty
 - ❑ Used for small targets, spherical targets
- ❑ Iris
 - ❑ Dodecahedron
 - ❑ Multiple beam apertures per robot position
 - ❑ Advantages: Efficient delivery, shorter treatment times
 - ❑ Used for spatially complex targets



MLC collimator

- ❑ MLC design:
 - ❑ 41 leaf-pairs, 9 cm thickness
 - ❑ 2.5 mm width at 80 cm
 - ❑ 12x10 cm at 80 cm
 - ❑ 100% over-travel and inter-digitation
 - ❑ Leakage <0.3% average, <0.5% max
 - ❑ Position reproducibility ± 0.4 mm
 - ❑ Step and shoot mode
- ❑ Advantages: Efficient delivery, treatment of large targets

Imaging System

- ❑ The imaging system provides a stereotactic frame of reference
- ❑ 2 diagnostic x-ray sources and 2 flat panel detectors
- ❑ It enables to track, detect & correct for patient and target motion.
- ❑ The isocenter is the reference point for robot calibration, treatment planning and image guidance.



Image guidance during treatment

- ❑ CyberKnife SRS is frameless
 - ❑ 6D Skull tracking
 - ❑ Alignment center
-
- ❑ Real-time, live images are compared against DRRs generated from planning CT at 45 degrees angle
 - ❑ Robot adjusts position based on this comparison

Patient setup

- ❑ Primary goal of immobilization: reproducibility, patient comfort
- ❑ Thermoplastic mask
- ❑ Soft padding

Image of mask

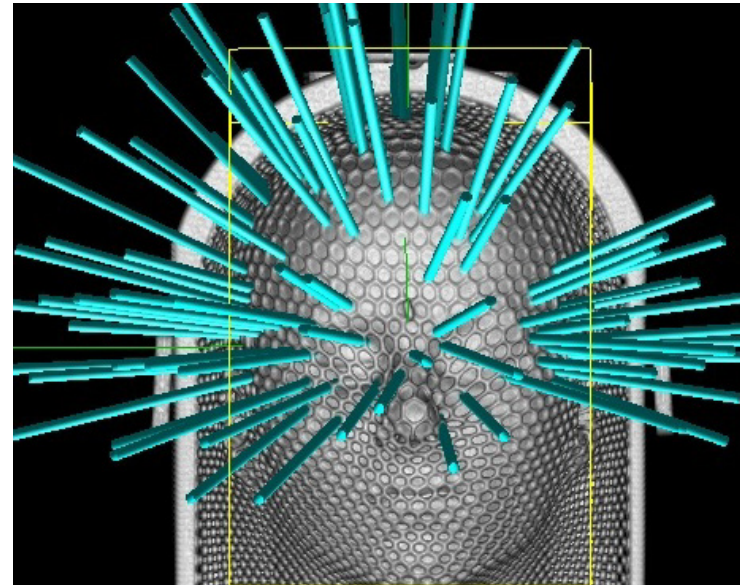
Imaging studies

- ❑ Primary CT scan used for dose calculation and DRR generation
- ❑ Secondary images used for target and OAR delineation (MRI, PET, contrast CT)
- ❑ Primary CT specifications:
 - ❑ Contiguous no gap, no contrast
 - ❑ Square acquisition (max 512x512x512)
 - ❑ Include anterior and superior aspect of mask with 1 cm margin

Image of fusion MR/CT

Treatment Parameters

- ❑ Number of fraction
- ❑ Treatment anatomy: head
- ❑ Template path set
- ❑ Tracking method: 6D Skull
- ❑ Collimator type



Align Center

- ❑ Set up image alignment center
- ❑ Maximize information on the DRR
- ❑ Align center does not depend on target location

Contours

- ❑ Manual
- ❑ Auto-segmentation for Brain
- ❑ Skin
- ❑ Max of 22 contours
- ❑ Need a couple open contours to do VOI operation

Plan setup

- ☐ CT density table
- ☐ Density override
- ☐ Dose calculation grid
- ☐ Beam blocking

Sequential Optimization

- ❑ Principles of sequential optimization
- ❑ Collimator selection
- ❑ MU limits
- ❑ Auto-shells
- ❑ Constraints and steps
- ❑ Time reduction
- ❑ Node reduction
- ❑ Beam reduction
- ❑ Prescription

Sequential Optimization

- ❑ In conventional optimization algorithms, multiple objectives are grouped in a single cost function.
- ❑ In sequential optimization, each objective (step) is optimized in sequence.
- ❑ The objective and the order of the steps define the clinical priorities.
- ❑ Auto-shells are tuning structures used to constrain the conformality and the extension of the low-dose region.
- ❑ Beam reduction removes all beams below a MU threshold and re-optimize the plans with the remaining beams while preserving the plan quality.
- ❑ Time reduction reduces the number of beams and nodes to achieve the user-defined time goal.

Sequential optimization

- ❑ Sequential optimization is divided between Maximum Dose Constraints and Dose Volume Constraints (hard constraints) and Dose Objectives (steps)
- ❑ Optimizer runs through the steps sequentially
- ❑ Objectives:
 - ❑ Target objectives
 - ❑ OAR objectives
 - ❑ Shells objectives
 - ❑ MU objectives
- ❑ Total number of sample points

Auto-shells

- ❑ Auto-shells are used to control dose conformity around the target and dose fall-off away from the target (dose fingers)

Image of auto-shells

Collimator size selection

- ❑ Spherical tumors – usually one collimator, a little larger than half the tumor size.
- ❑ Everything else – usually at least two, which are bound by the smallest target features and the largest collimator that fits in the target.
- ❑ Fixed – usually two, similar to these bounds.
- ❑ Iris – from the largest down to 12.5 or 10 mm.
- ❑ We never use 5 or 7.5 mm for the iris and only use them sparingly for fixed.

Image of a
complex target
with features

Courtesy of Neil Kirby

Dose calculation algorithms

- ❑ Ray Tracing:
 - ❑ Simple dose calculation method – equivalent path length
- ❑ Ray Tracing with contour corrections
 - ❑ Improved accuracy for oblique incidence (target near the surface)
- ❑ Monte Carlo
 - ❑ Most accurate dose calculation method – used in the presence of tissue heterogeneities (lung, spine, brain near the skull or air cavities)
- ❑ Ray tracing is adequate for treatment sites in the head with small tissue heterogeneity *

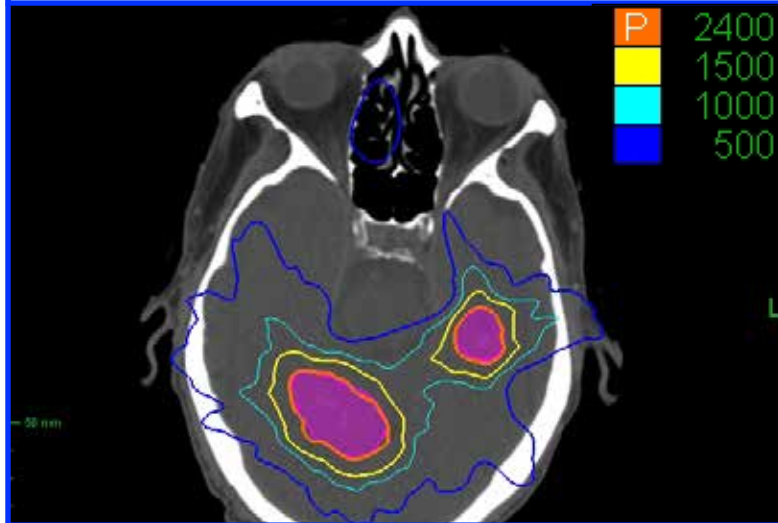
* Wilcox et al, PRO (2011) 1, 251

Plan Evaluation

- ❑ Evaluate the dose distribution everywhere in the patient
- ❑ DVH analysis
- ❑ Dose conformity – nCI
- ❑ Dose homogeneity – 1/IDL
- ❑ Low dose fingers
- ❑ Beam directions

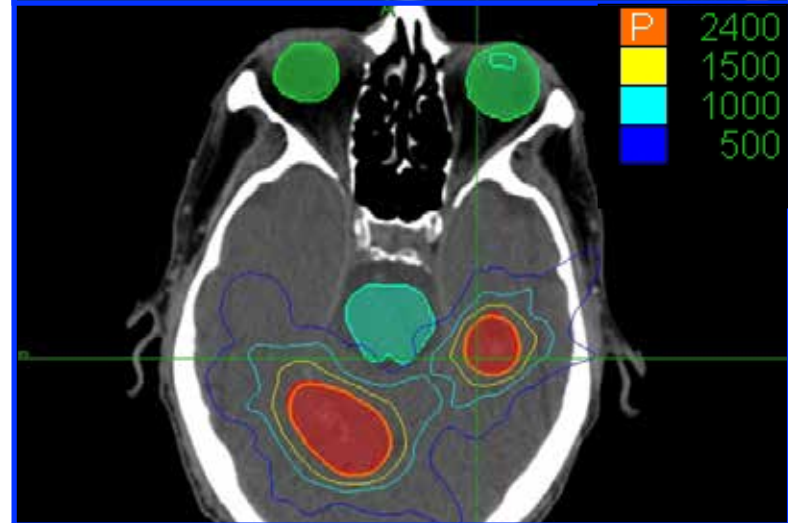
Multiple targets

CyberKnife - cones



- ❑ 24 Gy x 3 fx to 64%
- ❑ Beams: 166
- ❑ Tx time: 41 min
- ❑ Total MU: 39,600
- ❑ Brainstem $D_{\max}$: 10.5 Gy
- ❑ R50%: 4.4

CyberKnife MLC

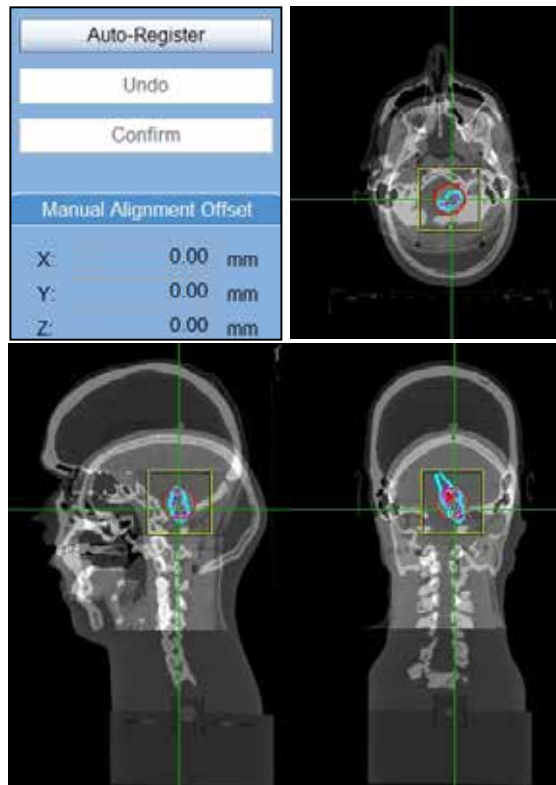


- ❑ 24 Gy x 3 fx to 73%
- ❑ Beams: 41
- ❑ Tx Time: 22 min
- ❑ Total MU: 13,200
- ❑ Brainstem $D_{\max}$: 9.4 Gy
- ❑ R50%: 3.6

Courtesy of Chris McGuinness, UCSF

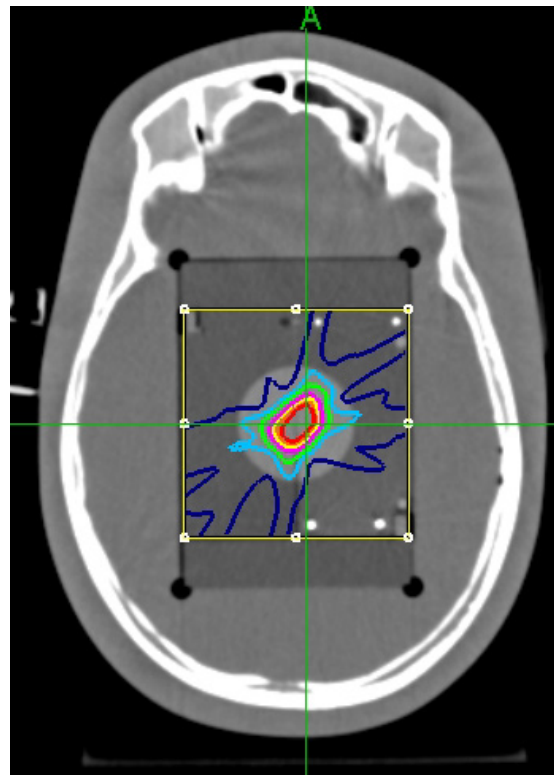
Dose Delivery QA

Image Registration



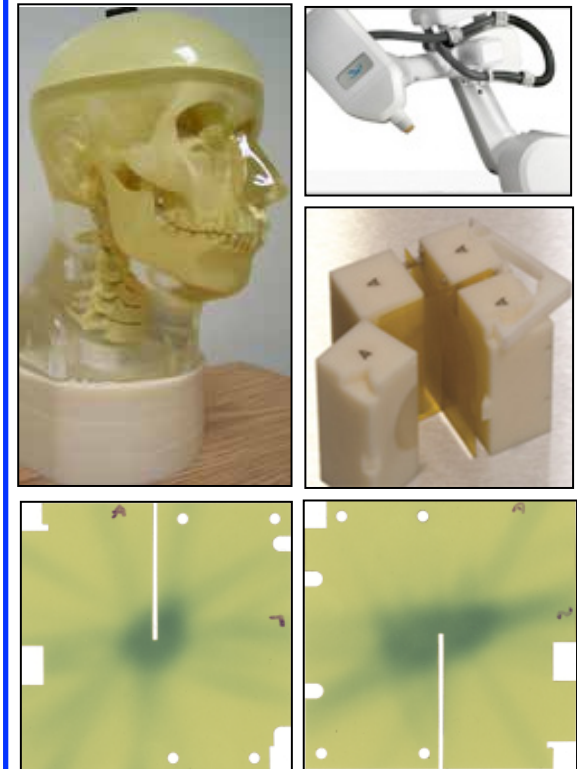
Align center of patient's target with center of phantom's target.

Dose Evaluation



Calculate corresponding dose distribution
Rescale MU < 700 cGy.

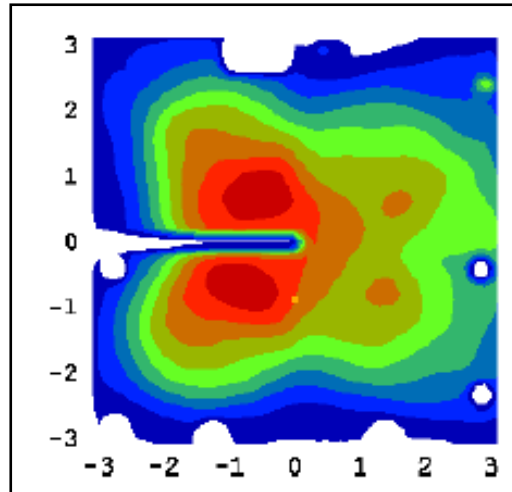
Plan Delivery



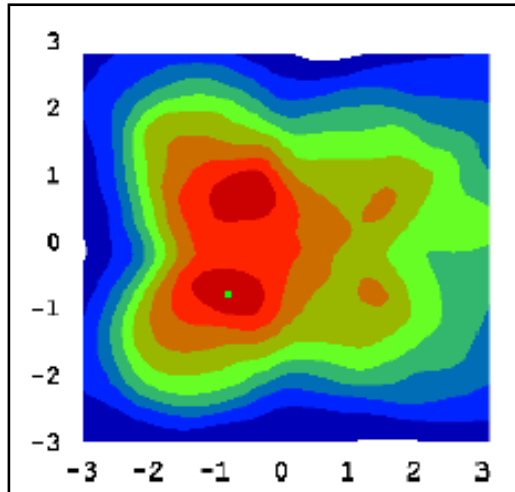
Deliver plan on phantom
Gafchromic EBT2 films
Axial & sagittal planes.

Film Analysis

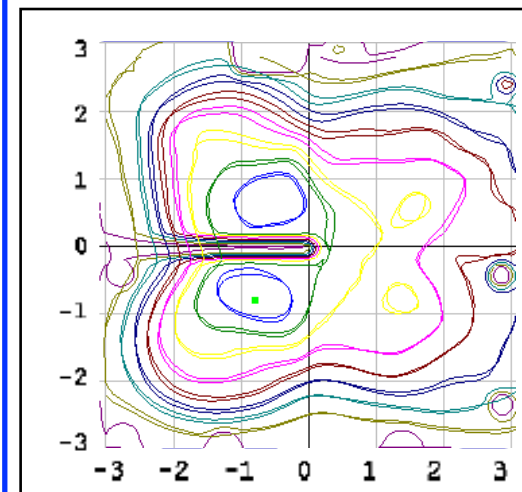
Film



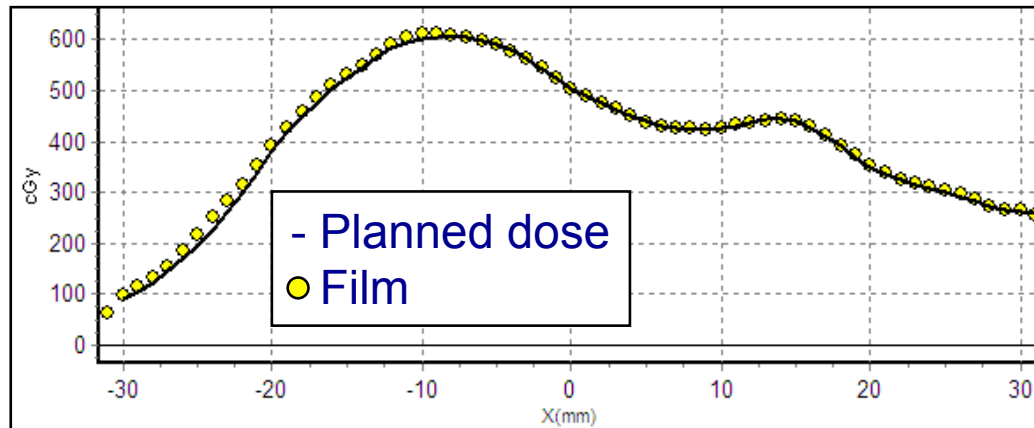
Planned dose



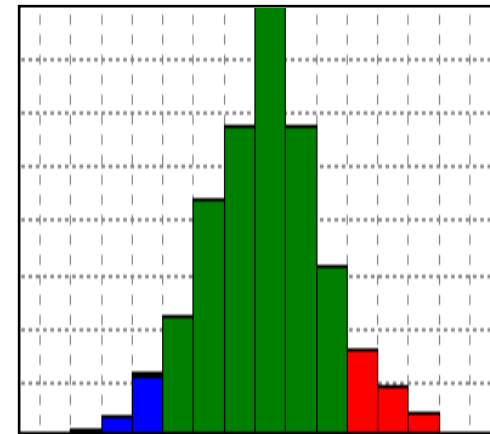
Dose comparison



Dose profile comparison



Statistical analysis



Targeting accuracy QA

- ❑ End to End
- ❑ AQA
- ❑ Table comparing the different QA test and frequency

Summary

- ❑ Take home message

Acknowledgments

- ❑ UCSF CK team
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