## Image Registration and Assessment for Adaptive Therapy

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#### Disclosure

" I have financial interest in deformable registration technology through a licensing agreement with RaySearch Laboratories

### Beautiful, Streamlined System Provides clear information



#### Hidden complexity: Several gears working seamlessly together



### Beautiful, Streamlined System Provides clear information



#### Hidden complexity: How do we get there?



#### Hidden complexity: How do we get there?



#### Why arend we there yet?

- "Pub Med search for <u>adaptive</u> radiotherapyqreturns 1098 citations (dating back to late 1990s)
- " At AAPM 2014 ~100 abstracts on adaptiveq
- " Many of the gearsqexistõ
- "However the lack of integration prohibits the widespread use of these tools on a large number of patients
- " Many of the gearsqare still missing
- "Underlying infrastructure often cannot support the extensive amount of data generated by dose accumulation/adaptive protocols





## **Clinical Implementation**

- Goal: to <u>safely</u> improve our ability to deliver the <u>optimal</u> treatment to each <u>individual</u> patient, <u>efficiently</u>, while contributing to the overall <u>knowledge</u> of the patient population
- " Need to understand and incorporate uncertainties
- "Must be a collaborative effort between vendors, physicists, and clinicians
- Wendors must provide the tools and information so that physicists can understand how to best implement the tools
- " Physicists must provide feedback to the vendors on what is needed and how the tools are working

## Tools Needed for Dose Accumulation & Adaptation

- 1. Images Obtained during Tx
- 2. Auto-Segmentation
- 3. Deformable Image Registration
- 4. Dose Re-calculation & Summation
- 5. Decision Making Tools
- 6. Plan Re-Optimization (including delivered dose)

### **Commissioning Image Registration**

- ″ LINAC
  - . Know how it works

Why is this particularly challenging for deformable registration?

"Algorithms typically don't rely on fundamental physics related to the human anatomy/physiology

- <sup>7</sup> Deformable Registration Algorithm
  - . Find out how it works!
  - . Accept and Commission the software
  - . Perform an end-to-end test in your clinic

#### Commissioning and QA Understand the whole picture



## Learning the Basics

#### How?

#### " AAPM Virtual Library

- . 2014 AM: Image Registration I: Deformable Image Registration, Contour Propagation and Dose Mapping: 101 and 201
- . 2014 AM: Image Co-Registration II: TG132-Quality Assurance for Image Registration
- . 2014 SCM: Image Registration for IGRT
- . 2014 SCM: Image Registration for Treatment Planning
- . 2013 AM: Deformable Image Registration, Contour Propagation and Dose Mapping: 101 and 201
- . 2013 AM: TG 132: Image Registration and Fusion
- . 2012 AM: Deformable Registration in the Clinic: From Commissioning To Advanced Applications
- . 2012 AM: Validation and QA of Deformable Image Registration Part II
- . The list goes on!
- "Several books and review papers

## Learning YOUR Clinicos Algorithm

#### How?

- <sup>7</sup> At minimum, the vendor should disclose:
  - . Similarity metric used
  - . Regularization used
  - . Transformation used
  - . Optimization method
  - . What knobs you can turn and what they do
- " Read white papers
- " Know that implementation matters

#### Why? Many Image Registration Techniques



# Why do we need to know the implementation?

#### Objective assessment of deformable image registration in radiotherapy: A multi-institution study

Rojano Kashani<sup>8)</sup> Department of Radiation Oncology, University of Michigan, 1500 E. Medical Center Drive, Ann Arbor, Michigan 48109-0010



#### New method to validate Deformable Image Registration

#### **Deformable 3D Presage dosimeters**





Control (No Deformation) Deformed (27% Lateral Compression)

Slides Courtesy of Mark Oldham and Shiva Das



DUKE UNIVERSITY MEDICAL PHYSICS GRADUATE PROGRAM

#### Dosimeter & Deformable Registration-based Dose Accumulation: Dose Distributions

**Field Shape Differences** 

#### **DVF-based**

nts

Caution must be used when accumulating dose, especially in regions of the image with homogeneous intensity.

Horizontal (Compression Axis)  $\rightarrow 40\%$  narrower to 175% wider

Vertical  $\rightarrow$  33% shorter to 50% taller

Slides Courtesy of Mark Oldham and Shiva Das

De

#### Different DIR Algorithms have Different Strengths and Weaknesses



Juang. IJROBP 2013;87(2): 414-421
 M Velec ASTRO 2014

## 1. The subtleties in the implementation of image registration are:

0% 1. Not important

0%

- Only important for someone who wishes to write their own algorithm
- 3. Less important than the ability to do purplegreen color blending
- Only important if it is a stand-alone image registration system
  - Important to know and for commissioning as they impact the accuracy of the algorithm

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REFERENCE: Brock KK and the Deformable Registration Accuracy Consortium, Results of a multi-institution deformable registration accuracy study (MIDRAS), IJROBP, 76 (2), 583-596, 2010

#### **Commissioning Toolbox**

" What tools do we have?

#### Visual Verification Excellent tool for established techniques Not enough for Commissioning



#### **Quantitative Validation Techniques**

#### Landmark Based

- . Does the registration map a landmark on Image A to the correct position on Image B?
- . Target Registration Error (TRE)
- " Contour Based
  - . Does the registration map the contours onto the new image correctly?
  - . Dice Similarity Coefficient (DSC)
  - . Mean Distance to Agreement (MDA)
- Digital/Physical Phantoms
  - . Compare known motion with registration results

#### Landmark Based (TRE)



Reproducibility of point identification is sub-voxel

- . Gross errors
- . Quantification of local accuracy within the target
- . Increasing the number increases the overall volume quantification
- Manual technique
- Can identify max errors
- Average vector distance between the points identified on Image A mapped onto Image B via the registration and the points identified on Image B = TRE

## That sounds great! Is that enough?



RMS = 0.3 mm

### Points Dond Tell the Whole Story



RMS = 0.3 mm

#### **Accuracy of Contours**



#### 2. Target registration error (TRE) is defined as

- 20% 1. the uncertainty in selecting landmarks on an image
- 20% 2. the average vector distance between the points identified on Image A mapped onto Image B via the registration and the points identified on Image B
- 20% 3. the improvement in accuracy when using deformable registration over rigid registration
- 20% 4. the volume overlap of 2 contours on registered images
- 20% 5. the mean surface distance between 2 contours on registered images

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REFERENCE: Fitzpatrick, J.M., J.B. West, and C.R. Maurer, Jr., Predicting error in rigid-body point-based registration. IEEE Trans Med Imaging, 1998. 17(5): p. 694-702.

## 3. Visual verification (e.g. split screen, blended images) following image registration

- 20% 1. is a quick method to perform qualitative validation of image registration in a clinical workflow following the quantitative commissioning of an algorithm
- 20% 2. has no role in a well-established program
- 20% 3. should be the essential component of commissioning
- **20%** 4. should never be used by the radiation oncologist
- 20% 5. should only be used by physicist with 20/20 vision

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REFERENCE: REFERENCE: Kessler ML, Image Registration and Data Fusion in Radiation Therapy (Review Article), BJR 79:S99-S108 2006

## 4. Image registration for adaptive radiotherapy is particularly challenging because

- 20% 1. the images are always multi-modality
- 20% 2. the patient cannot be imaged in an immobilization device
- **20%** 3. the second image must be at half-resolution
- 20% 4. the patient has typically responded to therapy, therefore the volume of tissue is not the same in both images
- 20% 5. deformable registration cannot be used in this case



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REFERENCE: Xing L, Lee, L, Timmerman R, Image-guided Adaptive Radiation Therapy and Practical Perspectives, Image-Guided and Adaptive Radiation Therapy, Lippincott Williams & Wilkins, 16-41.

#### Commissioning and QA Understand the whole picture



#### **Phantoms**



- Known attributes (volumes, offsets, deformations, etc.)
- Testing standardization .we all are using the same data
- Helps us learn specific aspects of the algorithm that are difficult to learn on clinical data
- May not include the complexities/noise of clinical images

## **Rigid Geometric Data**

- Helps us to learn the impact of the <u>knobsqof the</u> registration
- "Validation of most straightforward case
- *"* Similar to 20x20 field profile



\* Phantom Courtesy of ImSim QA, TG-132\* pending AAPM approval

## **Example Commissioning Tests**

AP         SI           Offset to Primary         dx         dy         dz           Defined         -10         5         -15           default, entire FOV         -10         5.1         -12.9           default, entire FOV         -9.9         4.5         -13.5           default, entire FOV         -10         4.9         -14.1           default, entire FOV         -10         5.2         -13.8           default, entire FOV         -3.3         4.4         -13.6           AVG         -9.64         4.82         -13.58           SD         0.75         0.36         0.44           AVG Deviation from Defined Offset         0.36         -0.18         1.42           Offset to Primary         dx         dy         dz           Defined         -10         5         -15
Offset to Primary         dx         dy         dz           Defined         -10         5         -15           default, entire FOV         -10         5.1         -12.9           default, entire FOV         -9.9         4.5         -13.5           default, entire FOV         -10         4.9         -14.1           default, entire FOV         -10         5.2         -13.8           default, entire FOV         -9.64         4.82         -13.58           SD         0.75         0.36         0.44           AVG Deviation from Defined Offset         0.36         -0.18         1.42           Offset to Primary         dx         dy         dz           Defined         -10         5         -15
Defined         -10         5         -15           default, entire FOV         -10         5.1         -12.9           default, entire FOV         -9.9         4.5         -13.5           default, entire FOV         -10         4.9         -14.1           default, entire FOV         -10         5.2         -13.8           default, entire FOV         -10         5.2         -13.8           default, entire FOV         -10         5.2         -13.8           default, entire FOV         -9.64         4.82         -13.58           SD         0.75         0.36         0.44           AVG Deviation from Defined Offset         0.36         -0.18         1.42           Offset to Primary         dx         dy         dz           Defined         -10         5         -15
default, entire FOV       -10       5.1       -12.9         default, entire FOV       -9.9       4.5       -13.5         default, entire FOV       -10       4.9       -14.1         default, entire FOV       -10       5.2       -13.8         default, entire FOV       -10       5.2       -13.8         default, entire FOV       -10       5.2       -13.8         default, entire FOV       -8.3       4.4       -13.6         AVG       -9.64       4.82       -13.58         SD       0.75       0.36       0.44         AVG Deviation from Defined Offset       0.36       -0.18       1.42         Offset to Primary       dx       dy       dz         Defined       -10       5       -15         User Defined (4th step with 4 mm resolution) entire FOV       40       5       -15
default, entire FOV       -9.9       4.5       -13.5         default, entire FOV       -10       4.9       -14.1         default, entire FOV       -10       5.2       -13.8         default, entire FOV       -8.3       4.4       -13.6         AVG       -9.64       4.82       -13.58         SD       0.75       0.36       0.44         AVG Deviation from Defined Offset       0.36       -0.18       1.42         Offset to Primary       dx       dy       dz         Defined       -10       5       -15
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default, entire FOV       -10       5.2       -13.8         default, entire FOV       -8.3       4.4       -13.6         AVG       -9.64       4.82       -13.58         SD       0.75       0.36       0.44         AVG Deviation from Defined Offset       0.36       -0.18       1.42         Offset to Primary       dx       dy       dz         Defined       -10       5       -15
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SD       0.75       0.36       0.44         AVG Deviation from Defined Offset       0.36       -0.18       1.42         Offset to Primary       dx       dy       dz         Defined       -10       5       -15         User Defined (4th step with 1 mm recelution) entire FOV       10       5       15
AVG Deviation from Defined Offset Offset to Primary Defined -10 5 -15 User Defined (4th step with 1 mm recelution) entire EOV
Offset to Primary dx dy dz Defined -10 5 -15
Defined -10 5 -15
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User Defined (4th step with 1 mm resolution), entire FOV -10 5 -15
User Defined (4th step with 1 mm resolution), entire FOV -10 5 -15
User Defined (4th step with 1 mm resolution), entire FOV -10 4.9 -15
User Defined (4th step with 1 mm resolution), entire FOV -10 5 -15
User Defined (4th step with 1 mm resolution), entire FOV -10 5 -15
AVG
SD 0.00 0.04 0.00
AVG Deviation from Defined Offset 0 -0.02 0

#### Commissioning and QA Understand the whole picture



## **DSC Evaluation on CT-CT DIR**



#### Data from 4 Clinical Cases

HN1002_REDO	DSC	DSC	DSC	I DSC	AVG DSC
ORAL_CAVITY1	0.78	0.85	0.89	0.89	0.85
SUBMAND_R1	0.67	0.97		0.82	0.82
CORD_PRV6	0.72	0.86		0.81	0.80
SUBMAND_L1	0.67		0.97	0.74	0.79
PAROTID_R1	0.76	0.84	0.74	0.76	0.77
BRAINSTEM1	0.74	0.89	0.81	0.58	0.76
LARYNX1	0.68		0.86	0.69	0.74
MANDIBLE1	0.80	0.68	0.67		0.71
PAROTID_L1	0.61	0.81	0.65	0.74	0.70
ESOPHAGUS1	0.71	0.62	0.73	0.71	0.69
CORD1	0.59	0.74	0.69	0.66	0.67
COCHLEA_L1	1.00	0.43	0.28	0.68	0.60
CONSTRICTOR_SUP1	0.29	0.85	0.52	0.65	0.58
LIPS1	0.60	0.54	0.67	l 0.37	0.54
CONSTRICTOR_INF1	0.13	0.50	0.42	0.60	0.41
COCHLEA_R1		0.18	0.34	0.06	0.19

#### Commissioning and QA Understand the whole picture



#### **Patient-Specific Clinical Evaluation**

- Multi-disciplinary education on information learned from commissioning
- "Know the visual tools available in clinical system
- " Develop procedure to do efficient quantitative evaluation when needed
- " Documentation!

#### **Example Implementation**

- Integrate with another documentIncluded in the Simulation Directive
- " Use drop-downs and check boxes
- " Include visuals when helpful

Imaging and Registration	
Primary Imaging:	
CT ABC: Yes No	
Secondary Imaging: MRI Date: MRI sim from perfusion protocol	
Series: Images:	3
Registration Technique: 🛛 Rigid 🔲 Deformable	1. Dome & Mid-liver
Local Region of Importance: 3 (Hepatic Duct) Comments:	2.Left Lobe
Intended use of Registered Images:	3. Liver Hilum
Tumor Definition 🔲 Normal Tissue Definition	4. Inferior of liver
Treatment Adaptation	-

Uncertainty Assessment	Phrase	Description
0	Whole scan aligned	<ul> <li>Anatomy within 1 mm everywhere</li> <li>Useful for structure definition everywhere</li> <li>Ok for stereotactic localization</li> </ul>
1	Locally aligned	<ul> <li>Anatomy local to the area of interest is un-distorted and aligned within 1mm</li> <li>Useful for structure definition within the local region</li> <li>Ok for localization provided target is in locally aligned region</li> </ul>
2	Useable with risk of deformation	<ul> <li>Aligned locally, with mild anatomical variation</li> <li>Acceptable registration required deformation which risks altering anatomy</li> <li>Registered image shouldn't be used solely for target definition as target may be deformed</li> <li>Increased reliance on additional information is highly recommended</li> <li>Registered image information should be used in complimentary manner and no image should be used by itself</li> </ul>
3	Useable for diagnosis only	<ul> <li>Registration not good enough to rely on geometric integrity</li> <li>Possible use to identify general location of lesion (e.g. PET hot spot)</li> </ul>
4	Alignment not acceptable	<ul> <li>Unable to align anatomy to acceptable levels</li> <li>Patient position variation too great between scans (e.g. surgical resection of the anatomy of interest or dramatic weight change between scans)</li> </ul>

Preliminary (not yet approved by AAPM) Recommendations from TG 132

# Example: Multi-modality imaging for Planning

#### Liver: CT (No Contrast = No visible GTV)





Liver: MR (Visible GTV)



Uncertainty Level: 2 Difficult to assess local accuracy, boundaries appear to match in local region Deformation is clear

## Summary

- <sup>"</sup> Deformable registration is a complex model
  - . Must understand the fundamentals of the model
  - . Commission and Validate the algorithm prior to clinical implementation
- Translation of geometric uncertainties to dosimetric error is complex and depends on complexity of motion and image intensity variation in the region
- "Implementation of adaptive RT requires multidisciplinary teamwork
- Physicists play a critical role in adaptive RT and communicating the right information to the right person in the right way is key