## Novel methods and tools for **MR Commissioning and Quality Control**

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#### **Disclaimer**

License agreement with Modus Medical Devices Inc. to develop a phantom for the quantification of MR image system-related distortions.

### **Topics for MR-guided RT system Commissioning & QC**

### MR data for RT planning and in-room guidance

- MR image distortion: system/scanner-related
- MR image distortion: susceptibility-induced
- Quantification of motion

### MR-guided systems: design specific

- RF noise
- Magnetic field coupling
- MR-radiation source system: iso-to-iso registration

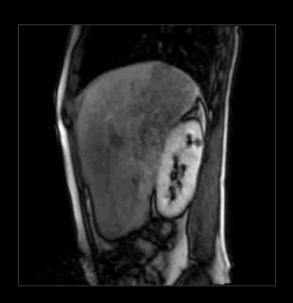
### System performance monitoring & Reporting

- Open-source software for semi/auto-QC monitoring
- Data base record: in-house, commercial, cloud solutions

#### MR data for RT planning

MR images suffer of intrinsic distortions → affect geometric accuracy

- > System | scanner related:
  - B0 field inhomogeneities
  - Imaging gradients non-linearity
- > Patient | object induced:
  - Tissue magnetic susceptibility
  - Chemical shift



- The distortions can be treated as separate problems
- Organ motion present → 4D composite distortion field

#### MR data for RT planning – System-related distortions

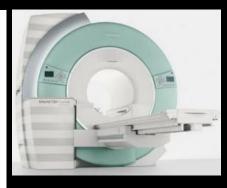
MR images suffer of intrinsic distortions → affect geometric accuracy

#### 1. B0 field inhomogeneities

- High field homogeneity required for the static magnetic field
- Typical value: a few ppm in a 40-50 cm spherical volume

#### Siemens Espree 1.5T - B0 field homogeneity specs

Homogeneity		
Volume	Guaranteed	Typical
10 cm DSV	≤0.05 ppm	0.01 ppm
20 cm DSV	≤0.2 ppm	0.08 ppm
30 cm DSV	≤1 ppm	0.8 ppm
$40 \times 40 \times 30 \text{ cm}^3$	≤2 ppm	1.2 ppm
$45 \times 45 \times 30 \text{ cm}^3$	≤4 ppm	2.8 ppm
		(Volume root-mean square) measured ane plot method (20 points per plane).
$40 \times 40 \times 40 \text{ cm}^3$	≤5 ppm*	



- 70 cm bore
- 120 cm long

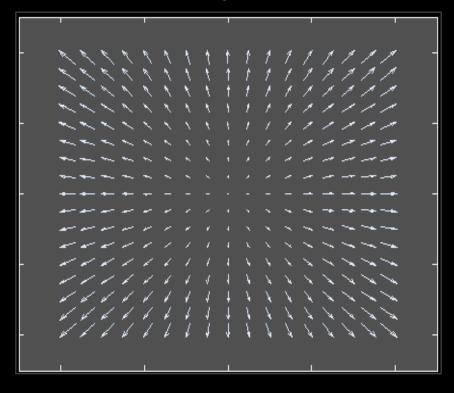
#### MR data for RT planning – System-related distortions

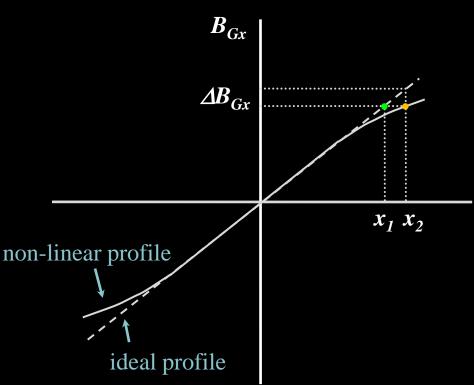
MR images suffer of intrinsic distortions → affect geometric accuracy

#### 2. Gradient non-linearity

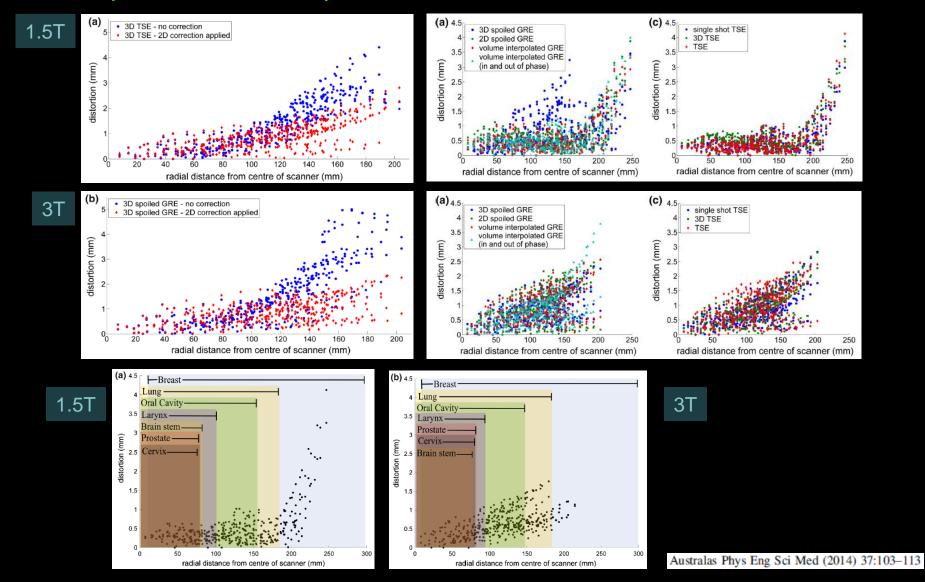
- Most significant source of geometric distortions

Distortion field magnitude ↑ with d-iso





## Multiple MR scanner quantification



#### MR data for RT planning – System-related distortions

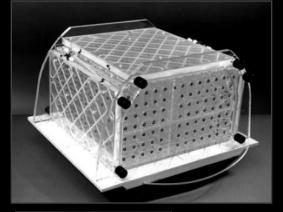
MR images suffer of intrinsic distortions → affect geometric accuracy

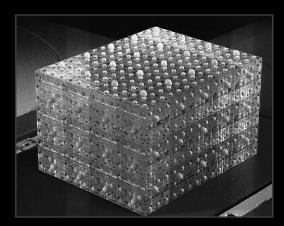
#### Methods for quantifying the 3D distortion field

- a. Measurements using phantoms or linearity objects
- b. Theoretical evaluation using spherical harmonics
- c. Hybrid approach

#### MRI Guidance

## System-related distortions









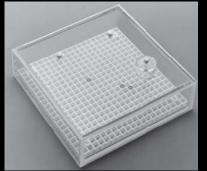






image processing algorithm

acquire data

identify control point locations

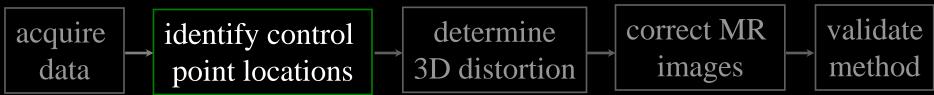
determine 3D distortion

correct MR images

validate method

#### MRI Guidance

## System-related distortions



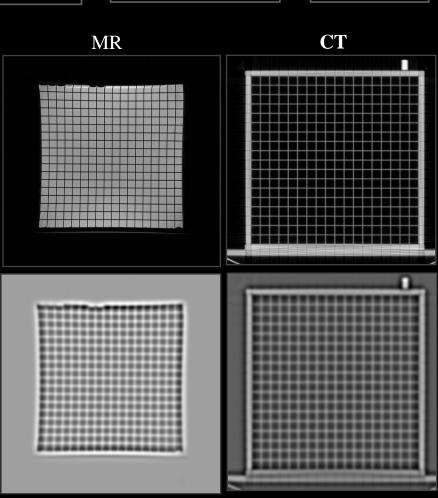
- unsharp mask and Gaussian blur
- adaptive thresholding
- 3D Gaussian blurring in x and y
- watershed: identify and analyze each dot
- center of mass: control points coordinates

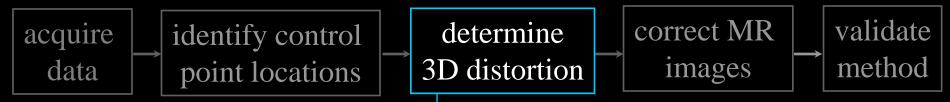
JOURNAL OF APPLIED CLINICAL MEDICAL PHYSICS, VOLUME 11, NUMBER 1, WINTER 2010

Investigation of a 3D system distortion correction method for MR images

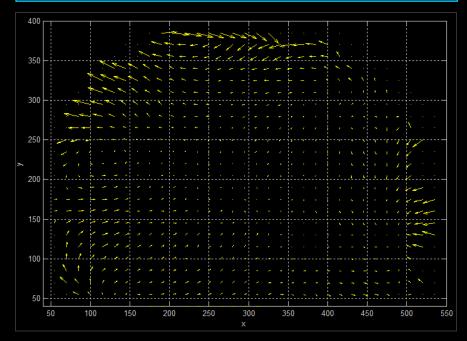
Teodor Stanescu,<sup>a</sup> Hans-Sonke Jans, Keith Wachowicz, Gino B. Fallone *Medical Physics, Cross Cancer Institute, Edmonton, AB, Canada teodorst@cancerboard.ab.ca* 

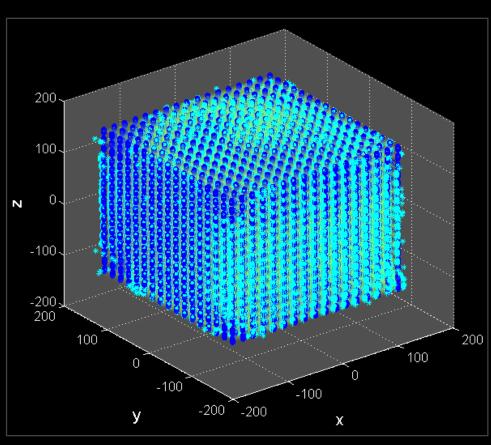
Received 10 October 2008; accepted 14 September 2009

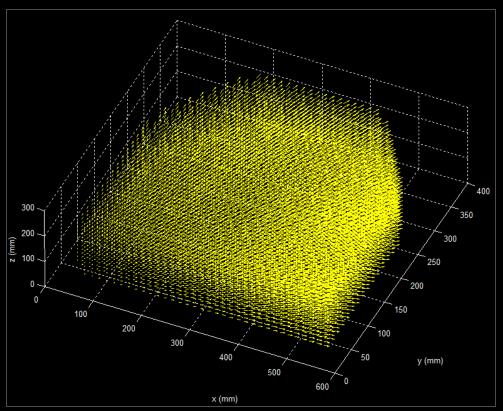


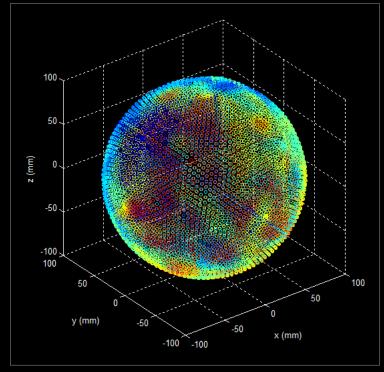


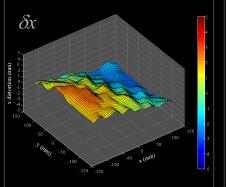
- register CT+MR control points
- clean data 3D polynomial fit
- determine 3D distortion field

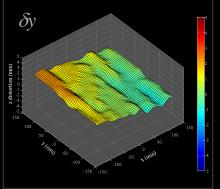


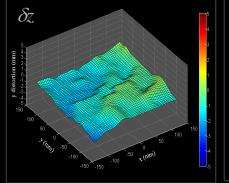


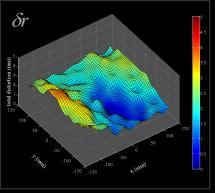






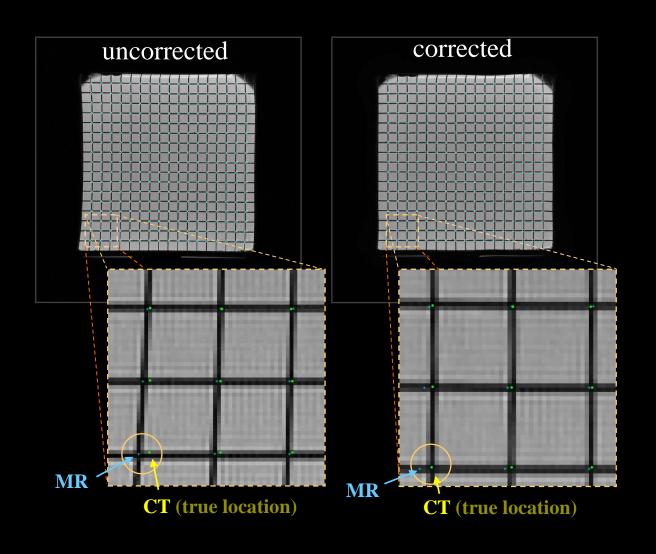


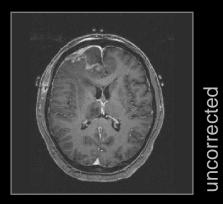


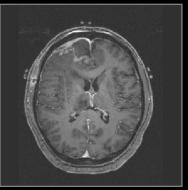


### MRI Guidance

## System-related distortions









difference

corrected

### Spherical harmonics analysis

## A complete distortion correction for MR images:

I. Gradient warp correction

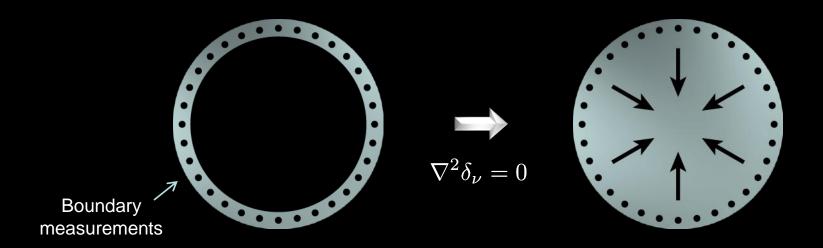
Simon J Doran<sup>1</sup>, Liz Charles-Edwards<sup>2</sup>, Stefan A Reinsberg<sup>2</sup> and Martin O Leach<sup>2</sup>

Phys. Med. Biol. 50 (2005) 1343-1361

$$B(r,\theta,\phi) = \sum_{n=0}^{\infty} \sum_{m=0}^{n} \left(\frac{r}{r_0}\right)^n P_{nm}(\cos\theta) [A_{nm}\cos m\phi + B_{nm}\sin m\phi],$$

- Anm, Bnm are the spherical harmonic coefficients
- Provided by the manufacturer for a certain region of interest
- Example: 29 coeff for Gx and Gy | 7 coeff for Gz

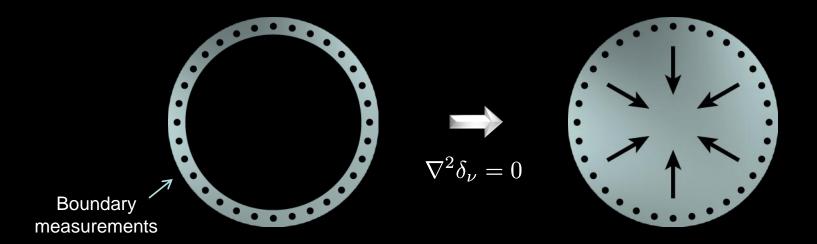
#### Hybrid technique: harmonics analysis + phantom measurements

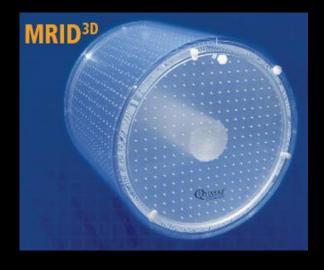


- Make use of the harmonic nature of the 3D distortion vector field
- Distortions measured on a volume boundary
- Laplace's equation is solved to reconstruct the full 3D distortion field within the entire VOI (volume of interest)

$$\delta_{\nu} = \sum_{i=1}^{N} c_{i,\nu} \Delta B_i(\vec{r}) \quad \nu \in \{x, y, z\} \quad \rightarrow \quad \nabla^2 \vec{B} = 0 \Rightarrow \nabla^2 \vec{\delta}(\vec{r}) = 0$$

## Hybrid technique: harmonics analysis + phantom measurements



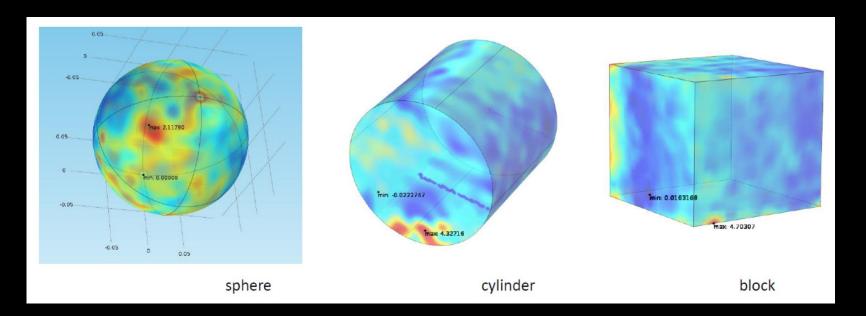


Collaboration with Modus Medical Devices

- Large field 3D distortions
- Harmonic analysis
- 38 diameter, 32 long
- Light weight, hollow, <17 Kg
- Option for inserts

### Harmonics analysis can be extended to arbitrary geometries

- Solver validated using reference data from a large FOV grid phantom
- Agreement with reference data: 0.1-0.5% of sampling points
- Validation for arbitrary surfaces ongoing Workflow
  - Source surface e.g. cylinder + grid extensions (incomplete MR coverage)
  - Surface parametrization volume meshing, set Dirichlet BC
  - Solver: solution for entire volume
  - Post-processing



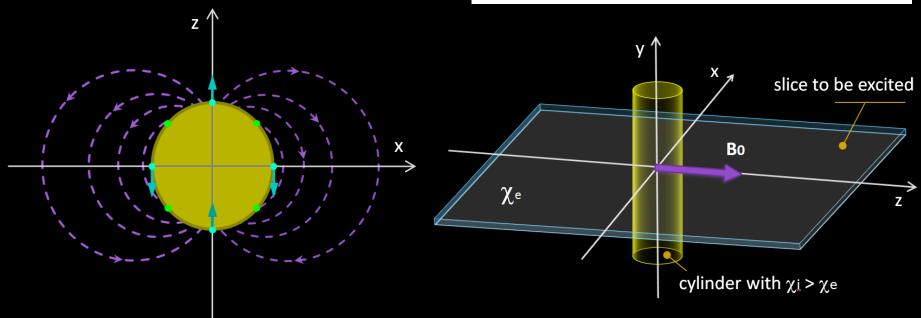
## **Summary**

- Manufacturers provide a 1<sup>st</sup> order correction (2D/3D)
- Detailed quantification depends on clinical applications
  - MR used for diagnostic
  - MR-only planning
- Limited standardization and lack of user friendly solutions

#### Tissue magnetic susceptibility

#### SUSCEPTIBILITY ARTEFACTS IN NMR IMAGING

K. M. LÜDEKE, P. RÖSCHMANN AND R. TISCHLER Philips GmbH Forschungslaboratorium Hamburg, D-2000 Hamburg 54, FRG



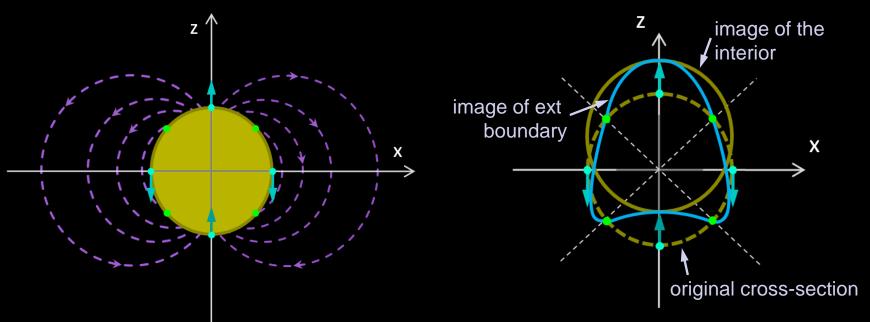
Cylinder geometry: interior and exterior mapped diff Interior: const field offset, no shape distortion along Gr

Exterior: (∃) inhomogeneous dipole field \ shape distortions

\ arrows indicate magnitude & direction of warp



#### Tissue magnetic susceptibility



Cylinder geometry: interior and exterior mapped diff Interior: const field offset, no shape distortion along Gr

Exterior: (∃) inhomogeneous dipole field

\ shape distortions

\ arrows indicate magnitude & direction of warp



## Methods for quantifying the distortion field:

- 1. Measurement of B0 field distortion map
  - double-echo GE sequence → phase diff of the 2 echoes
- 2. Correlating at least 2 images of the same sample
  - without calculating or measuring the field
- 3. Numerical computations of the magnetic field on datasets converted into tissue susceptibility maps

### Tissue magnetic susceptibility (~ mm)

## Characterization of tissue magnetic susceptibility-induced distortions for MRIgRT

#### T. Stanescua)

Med. Phys. 39 (12), December 2012

Radiation Medicine Program, Princess Margaret Hospital, 610 University Avenue, Toronto, Ontario M5G 2M9, Canada and Department of Radiation Oncology, University of Toronto, 610 University Avenue, Toronto, Ontario M5G 2M9, Canada

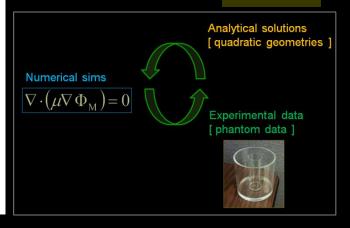
#### K. Wachowicz

Division of Medical Physics, Department of Oncology, University of Alberta, Cross Cancer Institute, 11560 University Avenue, Edmonton, Alberta T6G 1Z2, Canada

#### D. A. Jaffray

Radiation Medicine Program, Princess Margaret Hospital, 610 University Avenue, Toronto, Ontario M5G 2M9, Canada and Department of Radiation Oncology, University of Toronto, 610 University Avenue, Toronto, Ontario M5G 2M9, Canada

#### validation

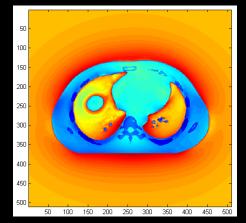


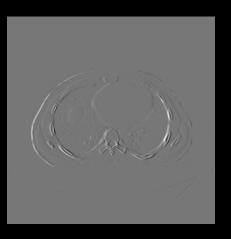
#### workflow











CT raw image

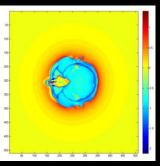
image mask

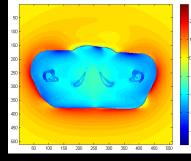
magnetic field

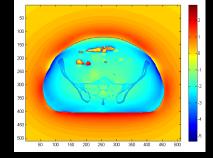
geometric distortion

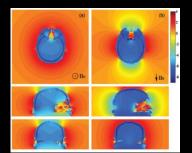
## Tissue magnetic susceptibility (~ mm)

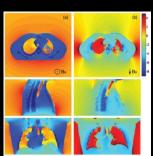
Anatomical site			Mean distortion (ppm)	Range of distortion (ppm)	0.5 T (5 mT/m)			3.0 T (5 mT/m)			
	Structure	Max distortion (ppm)			Max distortion (mm)	Mean distortion (mm)	Range of distortion (mm)	Max distortion (mm)	Mean distortion (mm)	Range of distortion (mm)	ppm offset
Brain	Body	5.48	0.43	9.36	0.55	0.04	0.94	3.29	0.26	5.62	-5.81
	Bone	3.36	0.25	6.37	0.34	0.03	0.64	2.02	0.15	3.82	
	Air cavities	5.66	0.92	9.96	0.57	0.09	1.00	3.40	0.55	5.98	
Lung	Body	2.99	0.41	5.37	0.30	0.04	0.54	1.79	0.25	3.22	-6.79
	Bone	4.96	0.64	7.71	0.50	0.06	0.77	2.98	0.38	4.63	
	Lung	5.56	0.71	8.85	0.56	0.07	0.89	3.34	0.43	5.31	
Prostate	Body	3.98	0.54	6.42	0.40	0.05	0.64	2.39	0.32	3.85	-6.07
(no air pockets)	Bone	2.48	0.41	3.03	0.25	0.04	0.30	1.49	0.25	1.82	
Pelvis	Body	3.91	0.46	5.91	0.39	0.05	0.59	2.35	0.28	3.55	-6.12
(air pockets)	Bone	2.54	0.47	4.02	0.25	0.05	0.40	1.52	0.28	2.41	
	Air pockets	4.85	0.68	7.27	0.49	0.07	0.73	2.91	0.41	4.36	



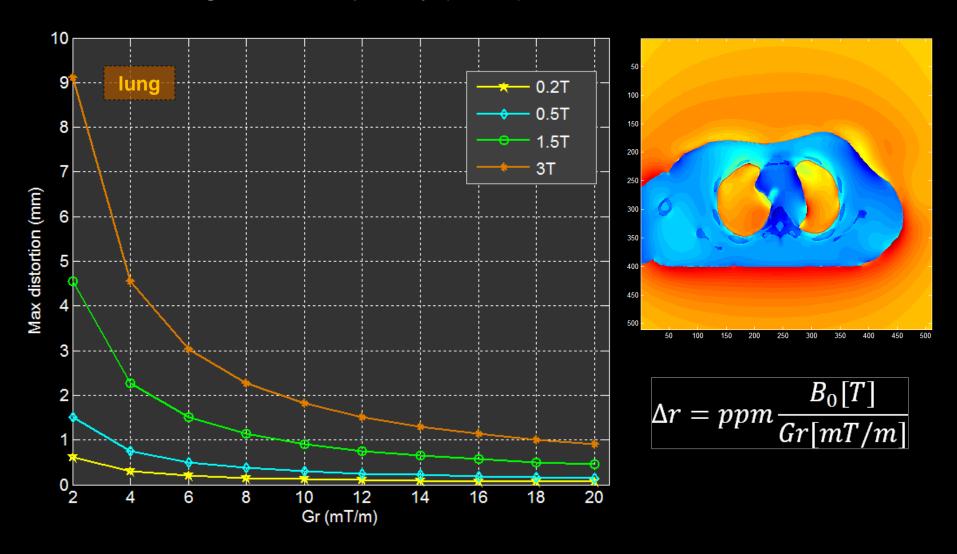








Tissue magnetic susceptibility (~ mm)



## Organ / target motion: lung

Case study: lung patient, 10 bins 4D CT

# 4D distortion field associated with organ motion:

- 2 independent steps

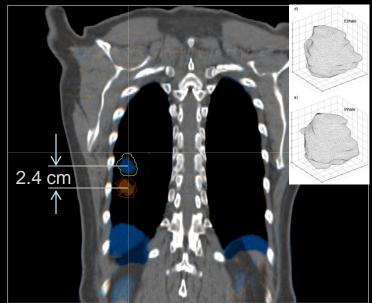
#### 1. System distortions

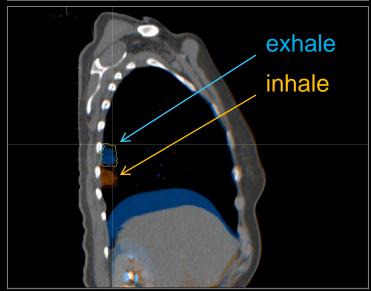
- register anatomy to 3D field
- track dist as local target/organs move
- static field measured with phantom

#### 2. Magnetic susceptibility

- numerical methods
- anatomy specific
- dynamic distortion field

Total: combine contributions from 1 & 2





## Organ / target motion: lung

### MRI Guidance

— B₀ z-axis

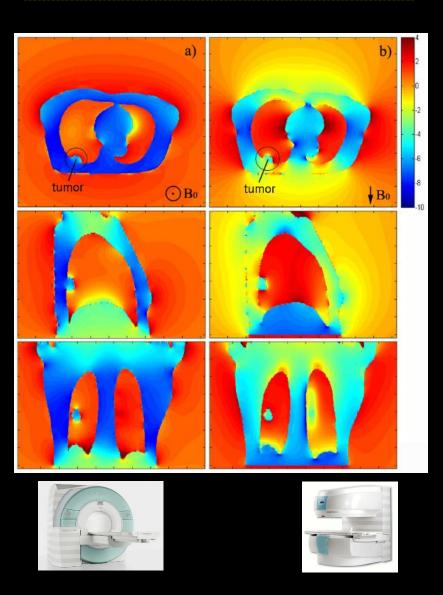
─ B<sub>0</sub> y-axis

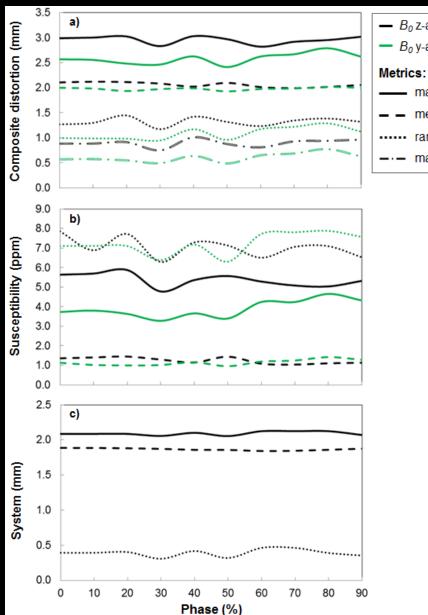
max

mean

max - mean

range





## Organ / target motion: lung

		Scanner-							
B0 z-axis		related field	χ-induced	χ-induced field			Composite Field		
				0.35 T	0.5 T	1.5 T	0.35 T	0.5 T	1.5 T
		[mm]	[ppm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
Exhale	max	2.13	5.29	0.37	0.53	1.59	2.11	2.11	2.82
	mean	1.84	1.08	0.08	0.11	0.32	1.87	1.89	2.01
	range	0.46	6.50	0.46	0.65	1.95	0.45	0.46	1.23
Inhale	max	2.09	5.64	0.39	0.56	1.69	2.20	2.29	2.99
	mean	1.89	1.36	0.10	0.14	0.41	1.92	1.94	2.10
	range	0.40	7.85	0.55	0.79	2.36	0.50	0.58	1.27

B0 y-axis		Scanner- related field	γ-induced	γ-induced field			Composite Field			
DO y axis			χ	0.35 T 0.5 T 1.5 T		0.35 T	0.5 T	1.5 T		
		[mm]	[ppm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	
Exhale	max	2.13	4.24	0.30	0.42	1.27	2.15	2.18	2.62	
	mean	1.84	1.19	0.08	0.12	0.36	1.86	1.87	1.97	
	range	0.47	7.72	0.54	0.77	2.32	0.49	0.57	1.17	
Inhale	max	2.09	3.73	0.26	0.37	1.12	2.08	2.11	2.57	
	mean	1.89	1.13	0.08	0.11	0.34	1.90	1.91	2.00	
	range	0.40	7.11	0.50	0.71	2.13	0.39	0.43	0.99	

#### MR data for RT planning

**Issue:** MR images suffer of intrinsic distortions → affect geometric accuracy

**Strategies:** Several methods proposed claiming adequate accuracy

#### **Limitations and Challenges:**

- Vendor and application specific
- Large FOVs still posing practical issues for distortion field mapping
- Susceptibility-induced distortions minimized via protocol optimization
- Real-time correction limited
- Streamlining and clinical integration

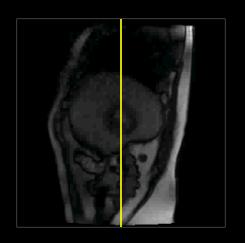
#### MR data for Treatment Delivery - Patient setup verification & Tracking/Gating

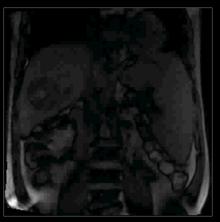
Aim: Reliable quantification and validation of methods used for organ motion assessment (real-time or retrospective data availability)

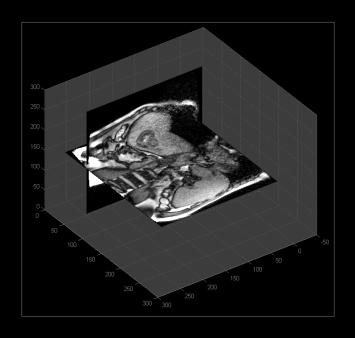
- Real-time imaging:
  - 1D / 2D readily available, platform specific
  - 3D → 4D (3D+time): most techniques under development
- Retrospective 4D image data binning and image reconstruction
  - Available, implementation is vendor specific
  - Growing literature: 2D → 4D, 3D → 4D

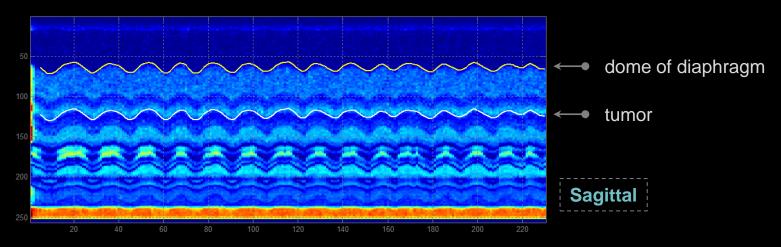
## 4D MRI Retrospective - 2D $\rightarrow$ 4D

### 2-plane sync: motion info







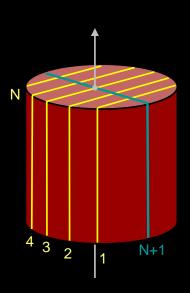


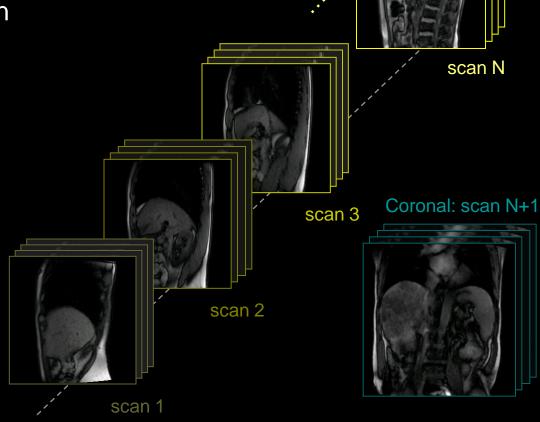
Sagittal: scans 1 to N

#### **4D MRI Retrospective - 2D → 4D**

#### Data acquisition

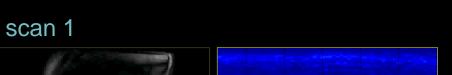
- 2D cine sagittal acquisition
- Multiple subsequent slice locations
- Cover volume of interest
- Additional coronal scan

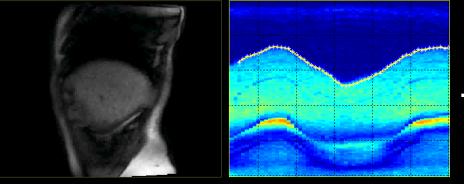




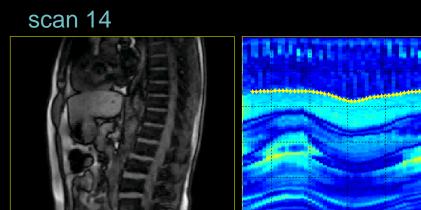
#### 4D MRI Retrospective - 2D $\rightarrow$ 4D

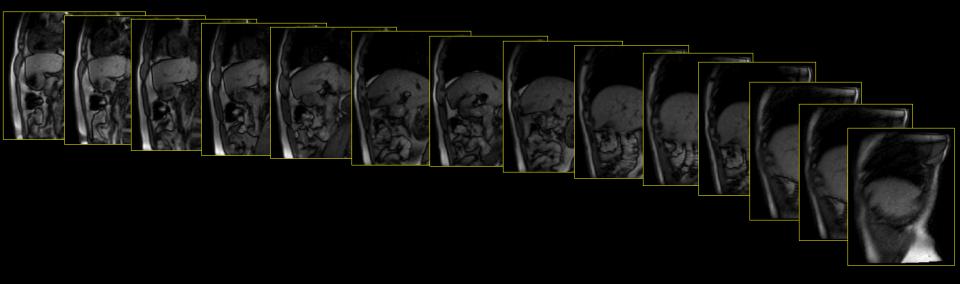
Organ motion curves & 4D data bining





Exhale phase – 3D volume, slice-by-slice





#### **4D MRI Retrospective - 3D → 4D**

- 3D fast acquisition with 4D image data sorting and reconstruction
- Similarity with 4D CBCT → potential solution for motion quantification

#### **Strategies:**

- Breathhold + multiple 3D acquisitions (< 15s) at diff respiratory phases</li>
- Free breathing Continuous acquisition (radial sampling) + post processing

#### **4D MRI Retrospective - 3D → 4D**

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- Free breathing Continuous acquisition (radial sampling) + post processing

#### **4D MRI Dynamic**

#### **Strategies:**

- Free breathing Multiple 3D scans with ~s time sampling, low image resolution
- Sparse/parallel imaging 3D acquisitions, good temporal sampling (?)

#### MRI Guidance

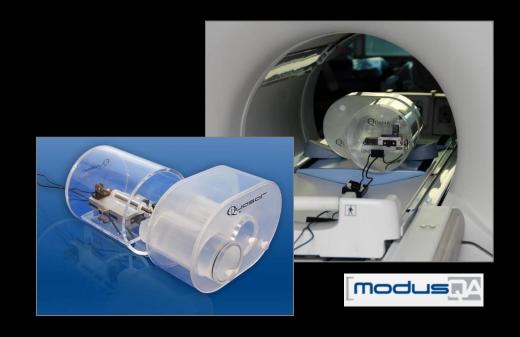
## QC of motion sequences: 2D/4D

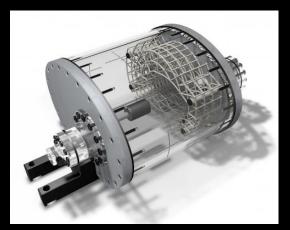


#### Motion Stage

- Accuracy in reaching a fixed position: 0.1 mm
- Maximum NRMSE for dynamic motion with frequency < 1 Hz: 6.0%
- Max speed: > 30 mm/sec
- Max force: -> 20 N
- Max phantom weight/load: 6 kg
- Dimensions: 134 mm W X 72 mm H (90 mm with phantom adapter) X 287 mm L
- Carriage: 102 mm W X 95 mm L
- Range of motion: 50 mm (2.0")



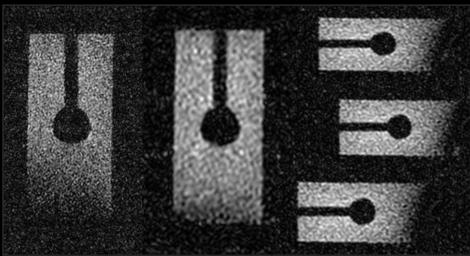




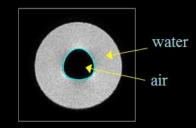


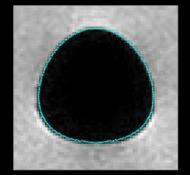
## **Phantom data analysis**

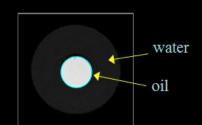








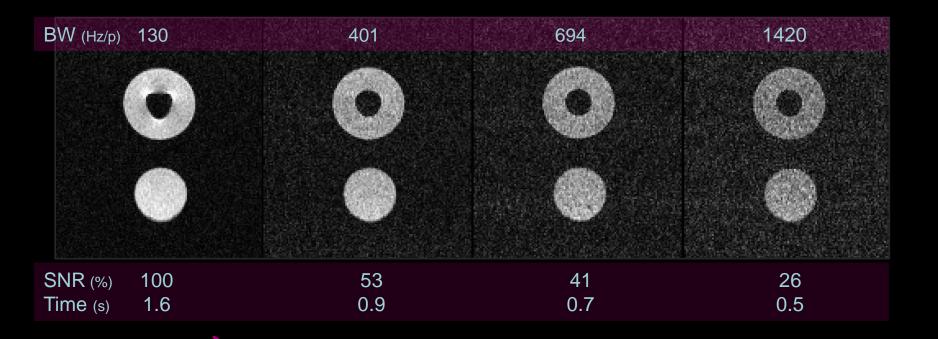






Prototype provided by Modus Medical Devices

## Phantom data analysis



Increased BW

**Decreased SNR** 

Decreased Susceptibility effects → better geometric accuracy

Decreased acquisition time/frame → faster imaging

**TurboFLASH** - 1.9x 1.9 x 8 mm | FOV 300 | min TE/TR

# **Phantom data analysis**

#### RadialVIBE:

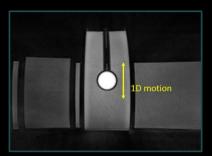
FOV: 310x310

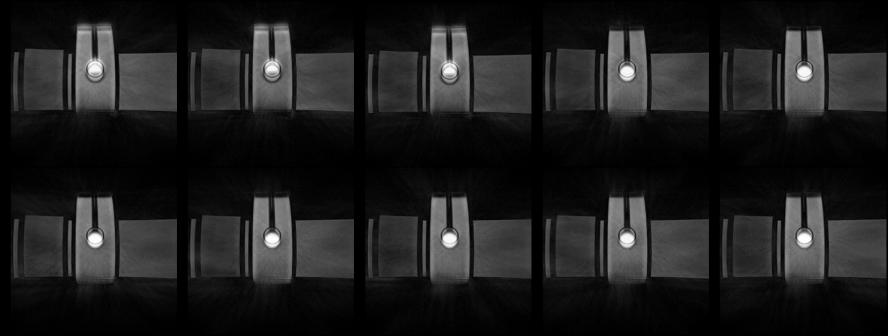
Voxel resolution 1.3x.1.3x3.0

Mid/High BW

View sharing mode: golden angle, total acquisition time < 1 min







#### MR data for Treatment Delivery - Patient setup verification & Tracking/Gating

Aim: Reliable quantification and validation of methods used for organ motion assessment (real-time or retrospective data availability)

Strategies: 1D / 2D available, several proposed 4D techniques

#### **Limitations and Challenges:**

- Vendor implementation and application specific
- 4D motion quantification of distortions still to be investigated
- Motion phantoms & QA methods still to be developed
- Motion data integration in clinical workflows

# Which is the main contributor to the MR image distortion field for RT applications?

27%	1.	MR main field (B0) inhomogeneity
6%	2.	Chemical shift
8%	3.	Tissue susceptibility
32%	4.	Imaging gradient non-linearities
27%	5.	Motion

# Which is the main contributor to the MR image distortion field for RT applications?

Answer: Imaging gradient non-linearities

Ref: Doran et al, Phys Med Biol 50, 1343-1361, 2005

#### System performance monitoring

- Open-source software for semi/auto-QC monitoring
  - ACR guidelines, AAPM, NEMA, etc.

#### MR data for RT planning and in-room guidance

- MR image distortion: system/scanner-related
- MR image distortion: susceptibility-induced
- Quantification of motion

#### MR-guided systems: design specific

- MR-radiation source system: iso-to-iso registration
- RF noise
- Magnetic field coupling

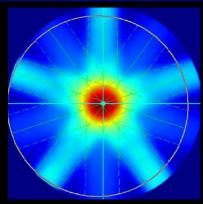
#### Reporting

- Data base record: in-house, commercial, cloud solutions

# MR-to-Radiation source isocenter registration

- Cylindrical phantom filled with water
- Scribe lines for alignment to lasers
- Circular film between two halves of phantom
- Wrap-around film strip
- Once MLC accuracy is established, imaging this phantom provides information about MR-RT isocenter alignment
- Once RT isocenter is established, MR isocenter coordinate shift is implemented in software

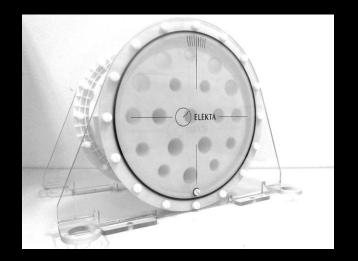


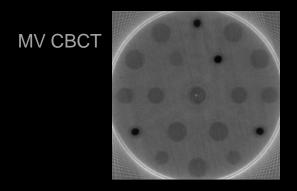


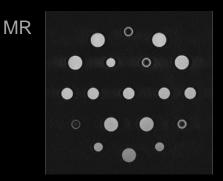
Courtesy of Olga Green, Washington University, St. Louis

# MR-to-Radiation source isocenter registration

- Designed for Elekta's Atlantic system
- MR-to-MV alignment
- Ceramic, non-conductive markers for MV
- 3D analysis to locate markers
- Automatic co-registration MR/MV
- Testing done at UMC, Utrecht
- MR image res: 1x1x1 mm3
- MV image res: 0.5x0.5x0.5 mm3
- Analysis mean error: ~0.3 mm



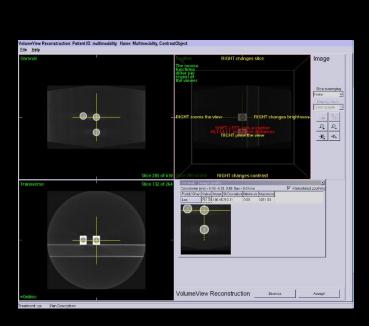




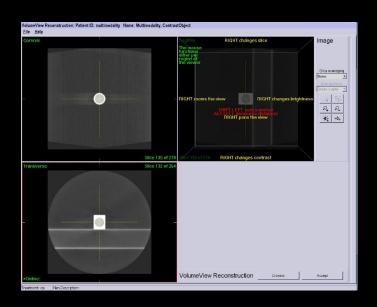
Images & info courtesy of M. Sell, M. Luzzaro (Elekta/Philips)

# MR-to-Radiation source isocenter registration

- Designed for IMRIS MR-linac system
- In collaboration with Modus Medical Devices
- MR-to-kV and MV alignment
- Daily QA
- 3D analysis to locate markers
- Automatic co-registration
- Ongoing testing







#### Radiofrequency (RF) interference

- MR needs to be isolated | Collects weak signal from patient
- Linac is a significant source of RF

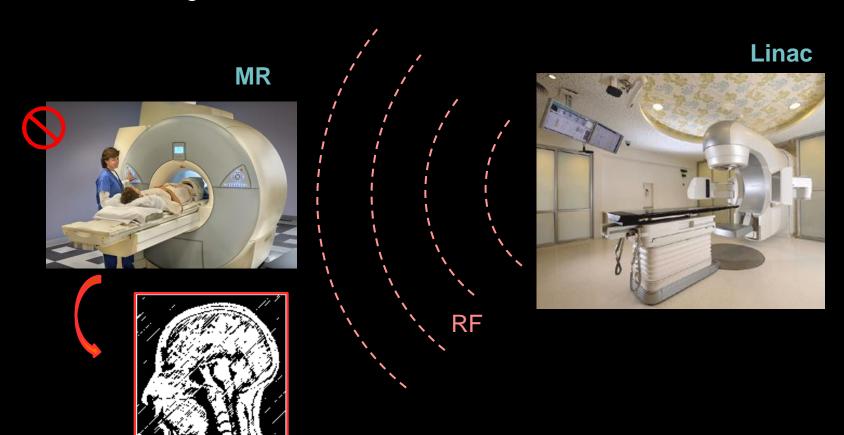
# MR RF shield

#### Linac



#### Radiofrequency (RF) interference

- MR needs to be isolated | Collects weak signal from patient
- Linac is a significant source of RF



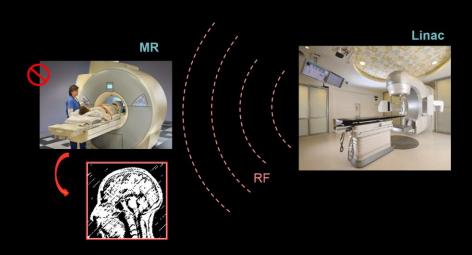
#### Radiofrequency (RF) interference

- MR needs to be isolated | Collects weak signal from patient
- Linac is a significant source of RF

#### Solutions:

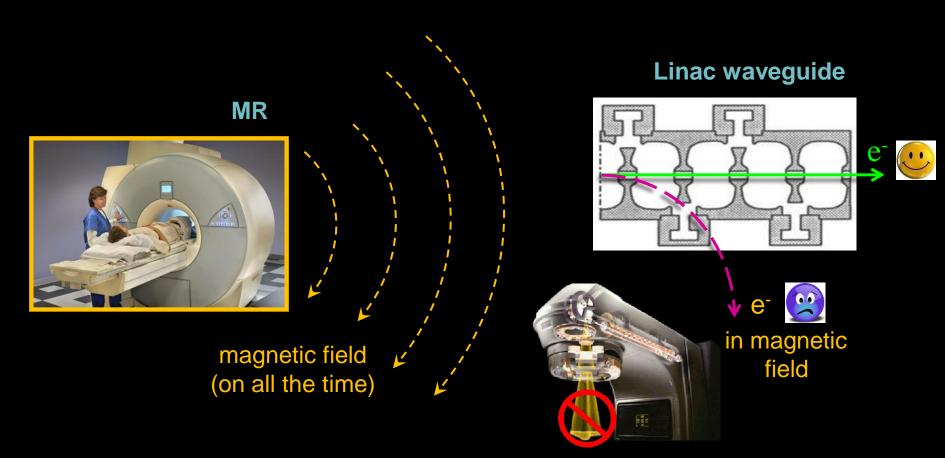
- Relocate linac main RF sources in adjacent rooms
- Enclose linac head or MR in a Faraday cage

- MR scanner RF noise tests
- RF sniffer kit for troubleshooting



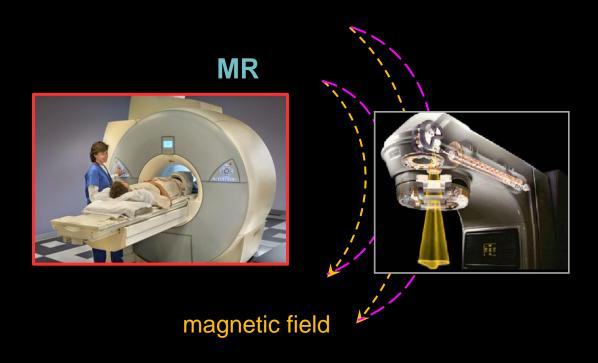
#### Magnetic field mutual interaction: MR magnet → Linac

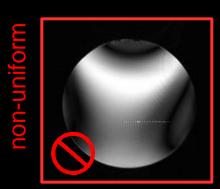
- B0 fringe field of MR scanner reaching the Linac structure
- Linac performance affected | Beam output = f(fringe B-field)

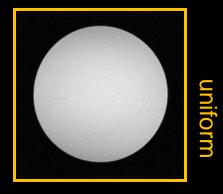


#### Magnetic field mutual interaction: MR magnet → Linac

- Linac is a large metallic structure, ferromagnetic components
  - » MR imaging field homogeneity affected







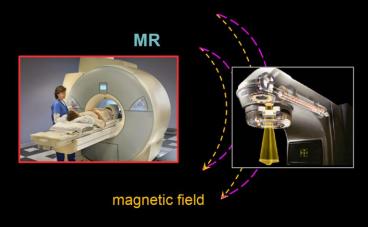
#### Magnetic field mutual interaction: MR magnet → Linac

- Linac is a large metallic structure, ferromagnetic components
  - » MR imaging field homogeneity affected

#### Solutions:

- Passive and/or active shielding
- Physical separation

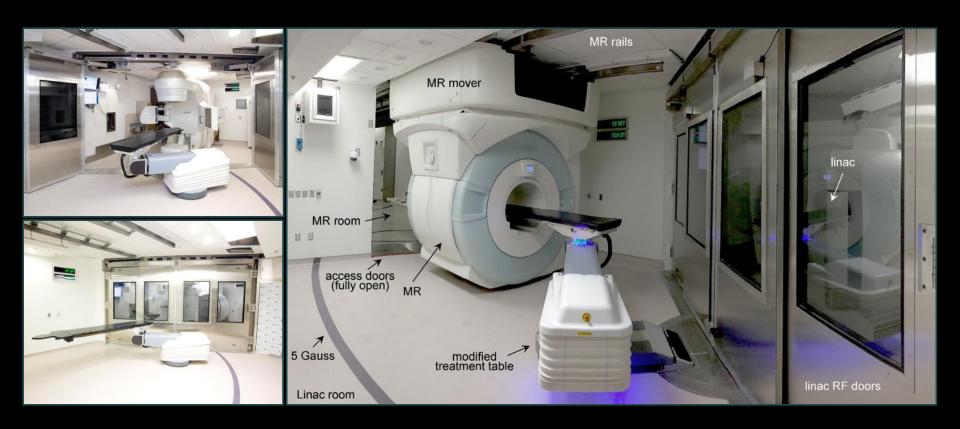
- Simulation environment: baseline, monitor perturbations
- MR: B0 mapping & Shimming
- Linac: rad beam, imaging



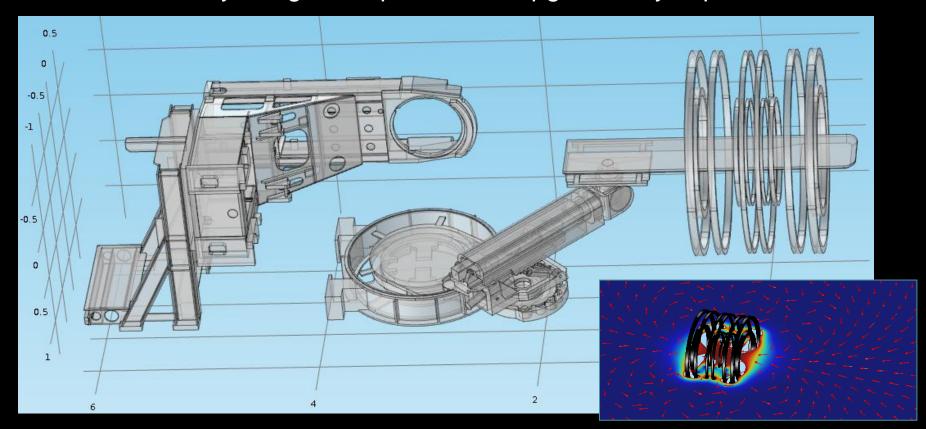




- Simulation environment: baseline for B0 fringe field mapping
- Establish margins of tolerance for sub-components
  - MR scanner: active imaging field homogeneity
  - Linac: beam optimal specs
  - Couch: safety margins on pull forces, upgradability impact on MR



- Simulation environment: baseline for B0 fringe field mapping
- Establish margins of tolerance for sub-components
  - MR scanner: active imaging field homogeneity
  - Linac: beam optimal specs
  - Couch: safety margins on pull forces, upgradability impact on MR



#### QC monitoring:

- B0 mapping for testing system performance
- Direct measurements to ensure B-field decoupling
  - MR should stay within specs over time, all intended configurations
  - Negligible impact from hysteresis/residual B-field related effects
  - Measurements more often than for a standalone MR implementation

1st order harmonics

tune-up











# **MR testing & commissioning**

**MRgRT: MR Shimming Study** 

#### **Methods:**

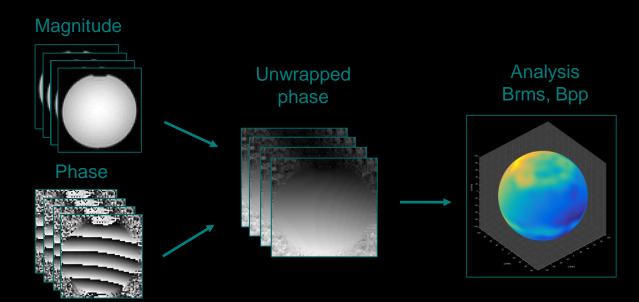
- Siemens service procedures: Phantom Shim & Phantom Shim Check
- B0 mapping technique: dual-echo GRE field mapping sequence
- Metrics: Brms, Bpp, FWHM water spectral peak

#### **Results:**

- Transient effects due to B-field priming of the environment
- The effects are reproducible
- MR shim stays within the specs outlined by Siemens/IMRIS

# B0 mapping technique:

Phantom



- Linac beam: Flatness & Symmetry v. Gantry angle rotation
- Direct measurements to ensure B-field decoupling
  - Beam stirring servos turned on/off
  - IC Profiler mounted on linac head via custom built accessory
  - Look for remnant magnetization and transient effects





#### QC monitoring:

- Linac beam: Flatness & Symmetry v. Gantry angle rotation
- Direct measurements to ensure B-field decoupling

180 195 210 225 240 255 270 285 300 315 330 345 360

- Beam stirring servos turned on/off
- IC Profiler mounted on linac head via custom built accessory
- Look for remnant magnetization and transient effects

flatness symmetry → Flatness X 101.500 100.5 → Flatness X MR 101.000 100.0 100.500 100.000 99 500 ★─Symmetry X MF 99.000 105 120 135 150 165 180 195 210 225 240 255 270 285 150 165 180 195 210 225 240 255 270 101.0 102.0 ──Flatness Y Symmetry Y 101 5 Flatness Y MR Symmetry Y MR 101.0 100.5 99.0

75 90 105 120 135 150 165 180 195 210 225 240 255 270 285 300 315 330 345 360

# For MR-guided RT systems, which MR-related test is new and has to be added to the QC routine?

10%	1.	Magnetic field drift
81%	2.	Imaging-to-treatment isocenter co-registration
4%	3.	Center frequency
3%	4.	Image uniformity
3%	5.	Ghosting

# For MR-guided RT systems, which MR-related test is new and has to be added to the QC routine?

Answer: Imaging-to-treatment isocenter co-registration

Ref: Lagendijk et al, Phys Med Biol 59, R349-R369, 2014

MR data for RT planning and in-room guidance

- MR image distortion: system/scanner-related
- MR image distortion: susceptibility-induced
- Quantification of motion

MR-guided systems: design specific

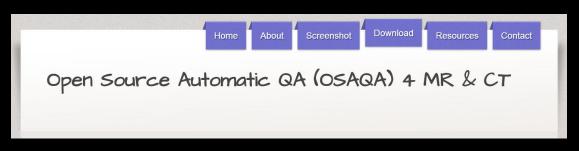
- RF noise
- Magnetic field coupling
- MR-radiation source system: iso-to-iso registration

#### System performance monitoring & Reporting

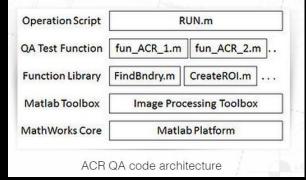
- Open-source software for semi/auto-QC monitoring
- Data base record: in-house, commercial, cloud solutions

#### System performance monitoring

- Open-source software for semi/auto QC analysis
  - Developed by J. Sun at el Calvary Mater Hospital, NSW
  - Supports ACR, MagPhan and MagIQ phantoms
  - Matlab code
  - Can be configured for broader purpose



http://qa-4-mr.webs.com/download http://jidisun.wix.com/osaqa-project



An open source automatic quality assurance (OSAQA) tool for the ACR MRI phantom

#### Data record and Reporting

#### In-house:

- AAPM 2015 presentation: TU-G-CAMPUS-I-15
  - Developed by J. Yung et al. at MD Anderson.
  - Semi-automatic QC program
  - Analyze and record measurements
  - Built on open-source software (Linux, Apache, MySQL, Python)
  - Analysis performed on 27 MR scanner: 1.5/3T, GE/Siemens
  - <u>Tests:</u> geometric accuracy/linearity, position accuracy, image uniformity, signal, noise, ghosting, transmit gain, center frequency, magnetic field drift

#### Data record and Reporting

#### **In-house / Commercial:**

- AQUA
  - Developed at Princess Margaret (Toronto)
  - Initially aimed for linac QC
  - Can be configured to include MRI tests
  - Analysis is semi-automatic
  - Data record is manual
  - Allows for data trending, control charts
  - The software is currently developed by Acumyn (www.acumyn.com)

#### Data record and Reporting

#### **Commercial / Cloud:**

- QUMULATE
  - Developed by Varian for linac QA
  - Store, visualize, manage QC data
  - Arbitrary tests can be configured
  - Potential platform for MRI
  - Monthly/annual fee for service

# MR-guided RT system Commissioning & QC

#### **Summary**

- Quantify and mitigate for system-related and patientinduced image distortions
- QC of motion sequences may be required, especially for new techniques
- MR-guided RT systems new tests may be required
  - RF noise
  - Magnetic field coupling
  - MR iso to radiation source iso co-registration
- Establishing a QC program including data reporting