# CT NOISE POWER SPECTRUM FOR FILTERED BACKPROJECTION AND ITERATIVE RECONSTRUCTION

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### Objectives

- Understand why Noise Power Spectrum(NPS) is a more comprehensive descriptor of CT image noise properties
- Be familiar with methods of evaluating NPS
- Understand why the NPS of Filtered Backprojection (FBP) differs from Iterative Reconstruction (IR)
- Be familiar with IR's noise property and its implication on CT protocol optimization

#### Same Noise Magnitude but Different Texture



120 kV, 1000 eff mAs, B70 Noise =16 120 kV, 10 eff mAs, B10 Noise =16

#### Why Noise Power Spectrum (NPS)?

- Noise (standard deviation) only measures the magnitude of image noise properties.
- Noise power spectrum measures not only the magnitude but also the spatial correlation of noise properties ("texture").

#### NPS for Images w/ Different Noise Texture



**B30** 

**B70** 

#### What information can we get from NPS?

- Area under NPS curve is equal to the square of noise (magnitude)
- Mean and peak frequencies are related to the noise texture (" noise grain size").
- Fine texture usually indicates NPS has higher mean and peak frequencies



#### **Evaluating CT Noise Power Spectrum**

- NPS is determined from the Fourier transform of the spatial autocorrelation function of a zero-mean noise image.
- For CT volumetric image data, NPS can be evaluated in 3D, 2D, or 1D (radially-averaged 2D)



#### **Equations for NPS Evaluation**

3D NPS: NPS<sub>3D</sub>
$$(f_x, f_y, f_z) = \frac{\Delta x \Delta y \Delta z}{N_x N_y N_z} < |DFT_{3D} \{I(x, y, z) - \overline{I(x, y, z)}\}|^2 >$$
  
2D NPS  $f_x f_y$ -plane: NPS<sub>2D</sub> $(f_x, f_y) = \frac{\Delta x \Delta y}{N_x N_y} < |DFT_{2D} \{I(x, y) - \overline{I(x, y)}\}|^2 >$   
2D NPS  $f_y f_z$ -plane: NPS<sub>2D</sub> $(f_y, f_z) = \frac{\Delta y \Delta z}{N_y N_z} < |DFT_{2D} \{I(y, z) - \overline{I(y, z)}\}|^2 >$ 

- I(x, y, z) is the CT volumetric image data, and  $\overline{I(x, y, z)}$  is the averaged image to remove the DC components and/or de-trending
- (...) is the ensemble mean
- 1D NPS is computed through radially-average of 2D NPS.

Siewerdsen et al, "A framework for noise-power spectrum analysis of multidimensional Images" Medical Physics, Vol. 29, No. 11, November 2002

#### **De-trend CT Images**

To de-trend and remove structured noise:

- By subtracting a polynomial fitted (2<sup>nd</sup> order) image from the original.
- For repeated acquisitions, use the difference image from two adjacent scans.
  - The NPS computed from the difference image should be divided by 2
  - To have the better de-trended image, make sure the tube starting angle is the same for the adjacent scans.

#### NPS Estimate Based on Single Acquisition



#### NPS Evaluation via Repeat Acquisitions

- For repeat acquisitions, the ensemble mean of NPS can be computed from images from repeat scans.
- The ensemble mean NPS tends to be less noisy for better estimate of mean and peak frequencies.

#### **Ensemble Mean NPS of Repeated Scans**

 NPS via ensemble mean of repeat acquisitions has smoother appearance than those from the single acquisition.



Yu et al, "Measurement and analysis of 3D NPS of an iterative reconstruction method in CT" RSNA 2012

#### Location-dependency of noise pattern



Yu et al, "Measurement and analysis of 3D NPS of an iterative reconstruction method in CT" RSNA 2012

#### Inter-vendor Comparison of Recon Kernels

For a CT site with more than one CT vendor, it is difficult to find matching recon kernels:

- GE: soft, standard, detail, chest, lung, bone, bone+, edge
- Siemens: B10f, B20f, B22f, B23f, B26f, B30f, B31f, B35f...
  B80f.
- Solomon et al. used similarity of the NPS to compare CT recon kernels between GE and Siemens

#### Phantom and ROI Placement

- Using module 3 (uniform section) of the ACR CT phantom
- Four ROIs in each slice and multiple slices in each acquisition



# **NPS Comparison Steps**

- Normalizing the 1D NPS by its integrated area -> nNPS
- Filtering nNPS with a human visual response function
- Root Mean Square Difference (RMSD) and Peak Frequency Difference (PFD) of NPSs as the metrics of similarity

#### Human Visual Response Function

 Human visual response function is used to account for the variable perception of noise by human at different spatial frequencies

$$\begin{split} \mathrm{nNPS}_{f}(r) &= \mathrm{nNPS}(r) \cdot |V(\rho)|^{2}, \\ \rho &= f \cdot \frac{\mathrm{FOV} \cdot R \cdot \pi}{D \cdot 180}, \\ V(\rho) &= |\eta \rho^{a_{1}} \cdot e^{-a_{2}\rho^{a_{3}}}|^{2}, \end{split}$$

 $nNPS_f(\mathbf{r})$  is normalized NPS by its area, V( $\rho$ ) is the human visual response function



#### Normalized NPS



Normalized NPS for GE recon kernels

#### Normalized NPS for Siemens recon kernels

#### **Relative Noise and Peak Frequencies**

TABLE II. Relative noise magnitude (normalized by the standard kernel) and peak frequencies of the  $nNPS_f(r)$  curves for GE kernels.

Relative noise	Peak frequency (mm <sup>-1</sup> )	
0.81	0.39	
1.00	0.43	
1.23	0.48	
1.23	0.46	
4.01	0.55	
3.38	0.75	
5.07	0.74	
6.39	1.03	
	Relative noise 0.81 1.00 1.23 1.23 4.01 3.38 5.07 6.39	

Relative noise and peak frequencies for GE recon kernels

TABLE III. Relative noise magnitude (normalized by the B43f kernel) and peak frequencies of the  $nNPS_f(r)$  curves for Siemens kernels.

Kernel	Relative noise	Peak frequency (mm <sup>-1</sup> )	Kernel	Relative noise	Peak frequency (mm <sup>-1</sup> )
B10f	0.44	0.29	B41f	0.86	0.44
B20f	0.56	0.33	B43f	1.00	0.43
B22f	0.62	0.37	B45f	1.26	0.45
B23f	0.62	0.37	B46f	1.18	0.49
B26f	0.57	0.36	B50f	1.93	0.52
B30f	0.69	0.37	B60f	3.98	0.62
B31f	0.74	0.42	B70f	4.39	0.61
B35f	0.66	0.39	B75f	3.71	0.62
B36f	0.75	0.44	B80f	4.38	0.55
B40f	0.84	0.40			

Relative noise and peak frequencies for Siemens recon kernels

#### Closest matched Siemens kernel for a GE kernel

TABLE IV. Closest matching Siemens kernel for a given GE kernel.					
GE	Siemens	RMSD (mm <sup>2</sup> )	PFD (mm <sup>-1</sup> )		
Soft	B35f	0.01	0.00		
Standard	B43f	0.01	0.00		
Chest	B41f	0.01	0.01		
Detail	B46f	0.04	-0.01		
Lung	B80f	0.03	0.00		
Bone	B75f	0.10	0.13		
Bone+	B75f	0.09	0.12		
Edge	B75f	0.18	0.41		

#### Noise Texture Comparison for Matching Kernels

Siemens Siemens GE GE B41f Soft B35f Chest Standard B43f Bone+ B75f B80f B46f Detail Lung

#### **CT** Iterative Reconstruction

 Is a feature that uses the information acquired during the scan and repeated reconstruction steps to produce an image with less "noise" or better image quality (e.g., higher spatial resolution or decreased artifacts) than is achievable using standard reconstruction techniques (FBP)

#### **CT** Iterative Reconstruction

 Iterative Reconstruction may be completed using data in Image Space, Projection (raw CT data) or a Model Based Approach. Projection or Model based approach is much better implementation but increases recon time.

#### **Model-based Iterative Reconstruction**



Repeat the loop until measured and synthesized projections converge

#### **Standard FBP Images**



Images courtesy of GE Healthcare

#### Model Based Iterative Recon (Veo) Images



Images courtesy of GE Healthcare

#### Nonlinear Statistics Model in IR

- In the statistics model of IR algorithm, there is an adaptive regularization term which depends on local contrast gradient, i.e., it can reduce the noise in homogeneous regions and preserve details at edges.
- The nonlinear regularization term may be more aggressive for noisier data.

#### Noise Comparison between FBP and IR



Chen et al, "Assessing CT Noise and Resolution for Nonlinear Reconstruction" Medical Physics, Vol. 41, No. 7, July 2014

#### FBP: NPS vs. Dose

The shape of normalized NPS is similar at different dose levels for FBP images



#### IR: NPS vs. Dose

 The shape of normalized NPS is not similar at different dose levels for IR images



# Peak Frequency for FBP and IR (Veo)



# Mean Frequency for FBP and IR (Veo)



#### Noise vs. Dose for FBP and IR (Veo)



#### Implications for Protocol Optimization in IR

- For IR protocols, the conventional relationship between noise and dose ( $\sigma = \alpha \cdot (mAs)^{-\beta}$ ,  $\beta = 0.5$ ) may not be valid anymore. Re-assessment of this important relationship under different dose levels is needed.
- In Veo (GE), β is between 0.21 and 0.25, which means the noise standard deviation is much less sensitive to the dose change. A 50% dose reduction will result in only 15% to 19% increase in noise. In FBP, that amount of dose reduction will lead to 40% noise increase.

#### Implications for Protocol Optimization in IR

- Noise texture may impact the detectability of low contrast lesion, especially using high strength IR.
- In general, IR will not degrade the high contrast resolution due to the fact that most IR uses adaptive regularization.

#### Conclusion

- NPS is a comprehensive descriptor for CT image noise properties, specifically related to noise texture
- Nonlinear iterative reconstruction tends to shift peak frequency of NPS curve towards lower value, but it doesn't necessarily mean degradation of high contrast resolution
- Noise vs. dose relationship for FBP may not be valid for IR due to its nonlinear regularization used in the statistical model
- Optimization of CT IR-based protocols should consider the implication of its nonlinearity on NPS